### Hash Tables

SDP-4

### Dictionary

### Dictionary:

- Dynamic-set data structure for storing items indexed using keys.
- Supports operations Insert, Search, and Delete.
- Applications:
  - Symbol table of a compiler.
  - Memory-management tables in operating systems.
  - Large-scale distributed systems.

#### Hash Tables:

- Effective way of implementing dictionaries.
- Generalization of ordinary arrays.



### Direct-address Tables

- Direct-address Tables are ordinary arrays.
- Facilitate direct addressing.
  - $\Box$  Element whose key is k is obtained by indexing into the  $k^{th}$  position of the array.
- Applicable when we can afford to allocate an array with one position for every possible key.
  - $\square$  i.e. when the universe of keys U is small.
- $\square$  Dictionary operations can be implemented to take O(1) time.
  - Details in Sec. 11.1.



### Hash Tables

#### Notation:

- $\Box$  U Universe of all possible keys.
- $\square$  K Set of keys actually stored in the dictionary.
- |K| = n.
- When U is very large,
  - Arrays are not practical.
  - $|K| \ll |U|$
- $\square$  Use a table of size proportional to |K| The hash tables.
  - However, we lose the direct-addressing ability.
  - Define functions that map keys to slots of the hash table.

# Hashing

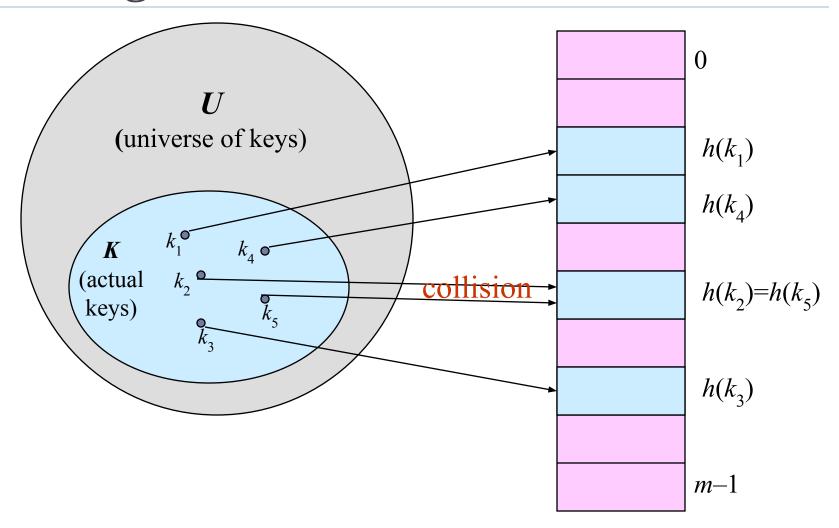
□ Hash function h: Mapping from U to the slots of a hash table T[0..m-1].

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h: U \rightarrow \{0,1,\ldots,m-1\}
```

- $\square$  With arrays, key k maps to slot A[k].
- □ With hash tables, key k maps or "hashes" to slot T[h[k]].
- $\Box$  h[k] is the *hash value* of key k.



# Hashing





# Issues with Hashing

- Multiple keys can hash to the same slot collisions are possible.
  - Design hash functions such that collisions are minimized.
  - But avoiding collisions is impossible.
    - Design collision-resolution techniques.
- $\square$  Search will cost  $\Theta(n)$  time in the worst case.
  - I However, all operations can be made to have an expected complexity of  $\Theta(1)$ .



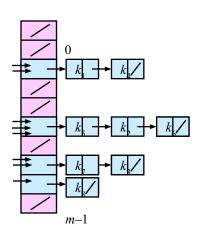
### Methods of Resolution

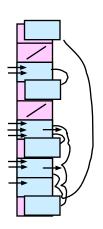
### Chaining:

- Store all elements that hash to the same slot in a linked list.
- Store a pointer to the head of the linked list in the hash table slot.

### Open Addressing:

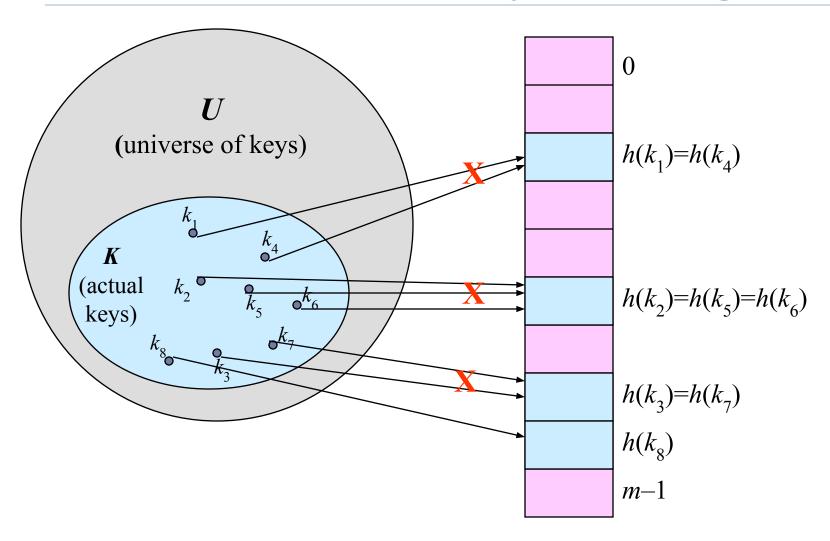
- All elements stored in hash table itself.
- When collisions occur, use a systematic (consistent) procedure to store elements in free slots of the table.





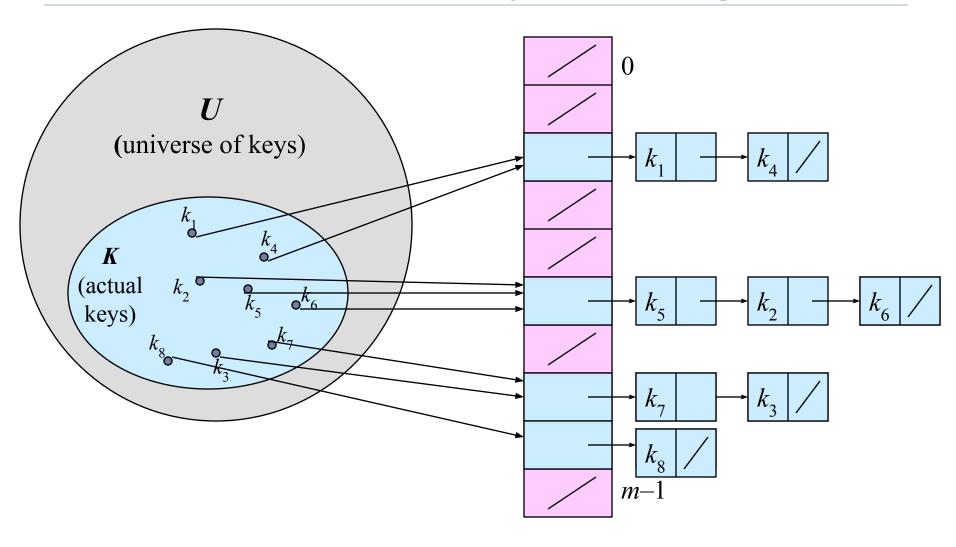


# Collision Resolution by Chaining





# Collision Resolution by Chaining



# Hashing with Chaining

### **Dictionary Operations:**

- $\Box$  Chained-Hash-Insert (T, x)
  - Insert x at the head of list T[h(key[x])].
  - □ Worst-case complexity -O(1).
- ☐ Chained-Hash-Delete (*T, x*)
  - Delete x from the list T[h(key[x])].
  - Under Worst-case complexity proportional to length of list with singly-linked lists. O(1) with doubly-linked lists.
- ☐ Chained-Hash-Search (*T, k*)
  - □ Search an element with key k in list T[h(k)].
  - Worst-case complexity proportional to length of list.



## Analysis on Chained-Hash-Search

- □ Load factor a=n/m = average keys per slot.
  - $\square$  m number of slots.
  - $\square$  n number of elements stored in the hash table.
- □ Worst-case complexity:  $\Theta(n)$  + time to compute h(k).
- $\square$  Average depends on how h distributes keys among m slots.
- Assume
  - Simple uniform hashing.
    - Any key is equally likely to hash into any of the *m* slots, independent of where any other key hashes to.
  - $\square$  O(1) time to compute h(k).
- □ Time to search for an element with key k is  $\Theta(|T[h(k)]|)$ .
- □ Expected length of a linked list = load factor =  $\alpha = n/m$ .



### Expected Cost of an Unsuccessful Search

#### **Theorem:**

An unsuccessful search takes expected time  $\Theta(1+\alpha)$ .

#### **Proof:**

- Any key not already in the table is equally likely to hash to any of the m slots.
- □ To search unsuccessfully for any key k, need to search to the end of the list T[h(k)], whose expected length is α.
- $\square$  Adding the time to compute the hash function, the total time required is  $\Theta(1+\alpha)$ .



# Expected Cost of a Successful Search

#### **Theorem:**

A successful search takes expected time  $\Theta(1+\alpha)$ .

#### **Proof:**

- The probability that a list is searched is proportional to the number of elements it contains.
- Assume that the element being searched for is equally likely to be any of the n elements in the table.
- The number of elements examined during a successful search for an element x is I more than the number of elements that appear before x in x's list.
  - These are the elements inserted after x was inserted.
- ☐ Goal:
  - Find the average, over the *n* elements *x* in the table, of how many elements were inserted into *x*'s list after *x* was inserted.



# Expected Cost of a Successful Search

#### Theorem:

A successful search takes expected time  $\Theta(1+\alpha)$ .

#### **Proof (contd):**

- Let  $x_i$  be the  $i^{th}$  element inserted into the table, and let  $k_i = key[x_i]$ .
- Define indicator random variables  $X_{ij} = \{h(k_i) = h(k_j)\}$ , for all i, j.
- ☐ Simple uniform hashing  $\Rightarrow \Pr\{h(k_i) = h(k_j)\} = 1/m$  $\Rightarrow E[X_{ij}] = 1/m$ .
- Expected number of elements examined in a successful search is:

$$E\left[\frac{1}{n}\sum_{i=1}^{n}\left(1+\sum_{j=i+1}^{n}X_{ij}\right)\right]$$

No. of elements inserted after  $x_i$  into the same slot as  $x_i$ .



### Proof - Contd.

$$E\left[\frac{1}{n}\sum_{i=1}^{n}\left(1+\sum_{j=i+1}^{n}X_{ij}\right)\right]$$

$$=\frac{1}{n}\sum_{i=1}^{n}\left(1+\sum_{j=i+1}^{n}E[X_{ij}]\right)$$

$$=\frac{1}{n}\sum_{i=1}^{n}\left(1+\sum_{j=i+1}^{n}\frac{1}{m}\right)$$

$$=1+\frac{1}{nm}\sum_{i=1}^{n}(n-i)$$

$$=1+\frac{1}{nm}\left(\sum_{i=1}^{n}n-\sum_{i=1}^{n}i\right)$$

$$=1+\frac{1}{nm}\left(n^{2}-\frac{n(n+1)}{2}\right)$$

$$=1+\frac{n-1}{2m}$$

$$=1+\frac{\alpha}{2}-\frac{\alpha}{2n}$$

(linearity of expectation)

### Expected total time for a successful search

- = Time to compute hash function + Time to search
- $= O(2+\alpha/2 \alpha/2n) = O(1+\alpha).$

## Expected Cost – Interpretation

- If n = O(m), then a=n/m = O(m)/m = O(1).
  - ⇒ Searching takes constant time on average.
- $\square$  Insertion is O(1) in the worst case.
- Deletion takes O(1) worst-case time when lists are doubly linked.
- $\square$  Hence, all dictionary operations take O(1) time on average with hash tables with chaining.



### Good Hash Functions

- Satisfy the assumption of simple uniform hashing.
  - Not possible to satisfy the assumption in practice.
- Often use heuristics, based on the domain of the keys, to create a hash function that performs well.
- Regularity in key distribution should not affect uniformity. Hash value should be independent of any patterns that might exist in the data.
  - $\square$  E.g. Each key is drawn independently from U according to a probability distribution P:

$$\sum_{k:h(k)=j} P(k) = 1/m$$
 for  $j = 0, 1, ..., m-1$ .

An example is the division method.

## Keys as Natural Numbers

- Hash functions assume that the keys are natural numbers.
- When they are not, have to interpret them as natural numbers.
- Example: Interpret a character string as an integer expressed in some radix notation. Suppose the string is CLRS:
  - ASCII values: C=67, L=76, R=82, S=83.
  - □ There are 128 basic ASCII values.
  - So, CLRS =  $67 \cdot 128^3 + 76 \cdot 128^2 + 82 \cdot 128^1 + 83 \cdot 128^0$ = 141,764,947.



### Division Method

 $\ \square$  Map a key k into one of the m slots by taking the remainder of k divided by m. That is,

$$h(k) = k \mod m$$

- $\square$  Example: m = 31 and  $k = 78 \Rightarrow h(k) = 16$ .
- Advantage: Fast, since requires just one division operation.
- Disadvantage: Have to avoid certain values of m.
  - Don't pick certain values, such as  $m=2^p$
  - Or hash won't depend on all bits of k.
- Good choice for m:
  - Primes, not too close to power of 2 (or 10) are good.



# Multiplication Method

- If 0 < A < I,  $h(k) = \lfloor m (kA \mod I) \rfloor = \lfloor m (kA \lfloor kA \rfloor) \rfloor$  where  $kA \mod I$  means the fractional part of kA, i.e.,  $kA \lfloor kA \rfloor$ .
- Disadvantage: Slower than the division method.
- Advantage: Value of m is not critical.
  - Typically chosen as a power of 2, i.e.,  $m = 2^p$ , which makes implementation easy.
- □ Example:  $m = 1000, k = 123, A \approx 0.6180339887...$   $h(k) = [1000(123 \cdot 0.6180339887 \mod 1)]$   $= [1000 \cdot 0.018169...] = 18.$

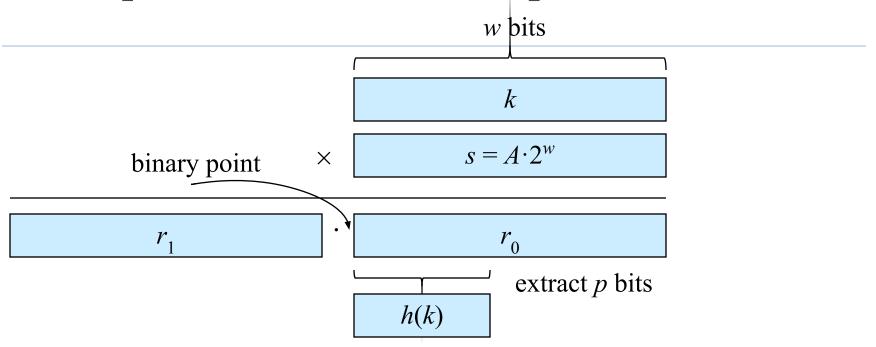


# Multiplication Mthd. - Implementation

- □ Choose  $m = 2^p$ , for some integer p.
- Let the word size of the machine be w bits.
- $\square$  Assume that k fits into a single word. (k takes w bits.)
- $\Box$  Let  $0 < s < 2^w$ . (s takes w bits.)
- $\square$  Restrict A to be of the form  $s/2^w$ .
- $\Box \text{ Let } k \times s = r_1 \cdot 2^w + r_0.$
- $\Gamma_1$  holds the integer part of  $kA(\lfloor kA \rfloor)$  and  $r_0$  holds the fractional part of  $kA(kA \mod 1 = kA \lfloor kA \rfloor)$ .
- $\square$  We don't care about the integer part of kA.
  - $\square$  So, just use  $r_0$ , and forget about  $r_1$ .



# Multiplication Mthd - Implementation



- We want  $[m (kA \mod I)]$ . We could get that by shifting  $r_0$  to the left by  $p = \lg m$  bits and then taking the p bits that were shifted to the left of the binary point.
- But, we don't need to shift. Just take the p most significant bits of  $r_{0}$ .



### How to choose *A*?

- Another example: On board.
- ☐ How to choose *A*?
  - The multiplication method works with any legal value of A.
  - But it works better with some values than with others, depending on the keys being hashed.
  - □ Knuth suggests using  $A \approx (\sqrt{5} 1)/2$ .

