

Кинематика	Законы сохранения	Основы МКТ	Электростатика	Индукция	Ядерные реакции
$v = \frac{S}{t} \dots x = x_0 \pm v \cdot t$ $S = x - x_0 = v \cdot t$ $a = \frac{\Delta v}{t} = \frac{v - v_0}{t}$ $v = \pm v_0 \pm a \cdot t$ $x = x_0 \pm v_0 \cdot t \pm \frac{a \cdot t^2}{2}$ $S = x - x_0 =$ $= v_0 \cdot t + \frac{a \cdot t^2}{2}$ $v^2 - v_0^2 = \pm 2a \cdot S$ $\Delta \varphi = \varphi_2 - \varphi_1$ $\omega = \frac{\Delta \varphi}{t} = \frac{2\pi}{T} = 2\pi \nu$ $v = \frac{1}{T} \dots S = \Delta \varphi \cdot R$ $v = \frac{S}{t} = \frac{\Delta \varphi \cdot R}{t} = \omega \cdot R$ $a_{ц} = \frac{v^2}{R} = \omega^2 \cdot R$	$\vec{F} \cdot \Delta t = \Delta \vec{p}$ $A = F \cdot S \cdot \cos \alpha$ $N = \frac{A}{\Delta t} \dots \eta = \frac{A}{W}$ $W_k = \frac{mv^2}{2} \dots W_p = mgh$	$W_{cp} = \frac{m_0 v_{ck}^2}{2}$ $n = \frac{N}{V} \dots p = \frac{2}{3} n W_{cp} \dots W_{cp} = \frac{3}{2} kT$ $v_{ck} = \sqrt{\frac{3kT}{m_0}} = \sqrt{\frac{3kN_A T}{\mu}} = \sqrt{\frac{3RT}{\mu}}$ $p = \frac{\nu RT}{V} \dots pV = \frac{m}{\mu} RT$	$F = k \frac{ q_1 q_2 }{r^2}$ $W_p = k \frac{q_1 \cdot q_2}{r} = Fd = qEd$ $\varphi = \frac{W_p}{q} = k \frac{q}{r} = Ed$ $A = -\Delta W_p = q(\varphi_1 - \varphi_2)$ $q = CU$ $C = \frac{\epsilon \epsilon_0 S}{d}$ $W = \frac{CU^2}{2} = \frac{q^2}{2C} = \frac{qU}{2}$ $W_p = \frac{q\varphi}{2}$	$F_L = qvB \sin \alpha$ $F_A = IB \sin \alpha$ $M = IBa \sin \alpha = ISB \sin \alpha$ $\Phi = BS \cos \alpha$ $H = \frac{I}{2\pi r}$ $\epsilon_H = -N \frac{\Delta \Phi}{\Delta t}$ $\epsilon_C = -L \frac{\Delta I}{\Delta t}$ $W_M = \frac{LI^2}{2} = \frac{\Phi I}{2} = \frac{\Phi^2}{2L}$	$mv_n r_n = \frac{h}{2\pi} n$ $v = \frac{E_1 - E_2}{h}$ $v_{\min} = R \left(\frac{1}{n^2} - \frac{1}{m^2} \right)$ $E_{\text{Я}} = E_H - E_{CB}$ $\Delta m = m_H - m_{\text{Я}} =$ $= (Zm_p + Nm_n) - m_{\text{Я}}$ $\Delta E = \Delta mc^2 =$ $= \Delta m \cdot 931,5 (M\text{эВ}) =$ $= (m_{\text{до}} - m_{\text{после}}) \cdot$ $\cdot 931,5 (M\text{эВ})$ $N = N_0 2^{\frac{t}{T_{1/2}}}$
	Механика жидкостей	Термодинамика	Постоянный ток	Квантовая физика	Основы СТО
	$p = \frac{F}{S}$ $p = \rho gh$ $\frac{h_1}{\rho_1} = \frac{h_2}{\rho_2}$ $F_A = \rho_{жк} V_{II} g$	$U = \frac{3}{2} \frac{m}{\mu} RT = \frac{3}{2} pV$ $\Delta U = \frac{3}{2} \frac{m}{\mu} \cdot R \cdot \Delta T$ $\Delta U = \frac{3}{2} p \Delta V \dots \Delta U = \frac{3}{2} \Delta p V$ $A = p \Delta V \dots Q = \Delta U + A$ $\Delta Q = C_T \Delta T \dots \Delta Q = cm \Delta T$ $\eta = \frac{A}{Q_1} = \frac{Q_1 - Q_2 }{Q_1} = 1 - \frac{ Q_2 }{Q_1}$ $\eta = \frac{T_1 - T_2}{T_1} = 1 - \frac{T_2}{T_1}$ $Q = \lambda m \dots Q = rm$	$I = \frac{\Delta q}{\Delta t} \dots R = \rho \frac{l}{S} \dots U = \varphi_1 - \varphi_2$ $I = \frac{U}{R} \dots I = \frac{\epsilon}{R+r}$ $A = \Delta q U = IU \Delta t = \frac{U^2}{R} \Delta t = I^2 R \Delta t$ $N = \frac{A}{\Delta t} = IU = \frac{U^2}{R} = I^2 R$ $Q = A = IU \Delta t = \frac{U^2}{R} \Delta t = I^2 R \Delta t$	$\epsilon = h\nu = \frac{hc}{\lambda}$ $\epsilon = mc^2$ $m = \frac{\epsilon}{c^2} = \frac{h\nu}{c^2} = \frac{hc}{c^2 \lambda} = \frac{h}{c \lambda}$ $p = mc = \frac{h\nu}{c} = \frac{h}{\lambda}$ $h\nu_0 = \frac{hc}{\lambda_0} = A + 0$ $v_0 = \frac{A}{h}$ $\lambda_0 = \frac{hc}{A}$ $h\nu = A + eU_3$	$l = l_0 \sqrt{1 - (v/c)^2}$ $t = \frac{t_0}{\sqrt{1 - (v/c)^2}}$ $v = \frac{v_1 + v_2}{1 + v_1 v_2 / c^2}$ $\vec{p} = \frac{m_0 \vec{v}}{\sqrt{1 - (v/c)^2}}$ $m = \frac{m_0}{\sqrt{1 - (v/c)^2}}$ $\Delta E = \Delta mc^2$ $E = mc^2$
Динамика	Колебания и волны	Оптика	Электромагнитные к-я	© Физика для незнайки	
$\vec{a} = \frac{\vec{F}}{m}$ $\vec{F} \cdot \Delta t = \Delta(m \cdot \vec{v})$ $F_{\text{млл}} = G \frac{m_1 \cdot m_2}{r^2}$ $F_{\text{млж}} = mg$ $v_{\text{гравит}} \text{ _хосмического} =$ $= \sqrt{\frac{G \cdot m_2}{R_2}} \approx 7,9 \text{ км/с}$ $F_{\text{тр}} = \mu \cdot N$ $\vec{F}_{\text{гпр}} = -k \Delta \vec{x}$ $M = F \cdot d$	$v = 1/T \dots F_{\text{упр}} = ma$ $x = X_m \sin(\omega t + \varphi_0)$ $v = x' = X_m \omega \cos(\omega t + \varphi_0)$ $a = x'' = -X_m \omega^2 \sin(\omega t + \varphi_0)$ $\omega = \sqrt{\frac{k}{m}} = \sqrt{\frac{g}{l}}$ $T = \frac{2\pi}{\omega} = 2\pi \sqrt{\frac{m}{k}} = 2\pi \sqrt{\frac{l}{g}}$ $W_k = \frac{mX_m^2 \omega^2}{2} \cos^2(\omega t + \varphi_0)$ $W_p = \frac{kX_m^2}{2} \sin^2(\omega t + \varphi_0) =$ $= \frac{mX_m^2 \omega^2}{2} \sin^2(\omega t + \varphi_0)$ $W = \frac{mX_m^2 \omega^2}{2} \dots \lambda = v \cdot T$ $x = X_m \sin(\omega t - kl)$	$n = \frac{c}{v_c} \dots \frac{\lambda_1}{v_1} = \frac{\lambda_2}{v_2}$ $n_1 \lambda_1 = n_2 \lambda_2$ $n_1 \sin \alpha = n_2 \sin \gamma$ $\alpha_{\text{пп}} = \arcsin \frac{n_2}{n_1}$ $D = \frac{1}{F} = \frac{1}{d} + \frac{1}{f}$ $\Gamma = \frac{H'}{H} = \frac{f}{d}$ $\Delta \Phi = 2\pi \frac{\Delta l}{\lambda}$ $\Delta l = 2k(\lambda/2)$ $\Delta l = (2k+1)(\lambda/2)$ $d \sin \varphi_k = \pm k \lambda$ $d = \frac{N}{l}$	$q = q_m \cos(\omega t + \varphi_0)$ $I = -q_m \omega \sin(\omega t + \varphi_0)$ $W_3 = \frac{q^2}{2C} \dots W_M = \frac{LI^2}{2}$ $\epsilon = \epsilon_m \cos \omega t$ $I = I_m \cos \omega t$ $U_R = IR = I_m \cos \omega t$ $U_L = I_m L \omega \cos(\omega t + \pi/2)$ $q = \frac{I_m}{\omega} \cos(\omega t - \pi/2)$ $U_C = I_m \frac{1}{C\omega} \cos(\omega t - \pi/2)$ $\omega = \frac{1}{\sqrt{LC}}$ $T = \frac{2\pi}{\omega} = 2\pi \sqrt{LC}$		