

Quick Start Software Training



Overview

- Software overview
- RTU overview
- Start an ISaGRAF Open project
- Configure an RTU using SXTOOLS (basic setup with tags, & export)
- Develop simple program and "Build" (compile) ISAGRAF project
- Download to RTU using the Tool Kit and ISaGRAF



SIXNET Tool Kit

- •Used to configure, load, and maintain SIXNET Automation RTUs and I/O
- Project Management software
- Works with ISaGRAF Open programming software

SCSDEMO_IPM_REDUNDANCY.6PJ	J - SI)	KNET I/) Tool Kit				
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Tree Views		Status	Station Name	Station / Number /	Station Type	Connected To	Serial Number
By LINK SIXIOG	1	ок	Pump_station_P	1	VT-IPM-1410	Citect: SxDirect	20678
All Stations	2	ок	SCSDemo_IO_P	2	ET-8DI2-8DO2-H	IPm:Pump_station	24850
🕀 🔽 Ethernet Stations	3	OK	Pump_station_S	3	VT-IPM-1410	Citect: SxDirect	20680
IPm Remote Terminal Units	4	ок	SCSDemo_IO_S	4	ET-8DI2-8DO2-H	IPm:Pump_station	4
	5	OK	NewSta5	5	ET-GT-ST-2	Not Determined	N/A
Pump_station_5	6						
< >			1 <u>2</u>				
	< >	Station	s (Location Ports)	All Tags An	alogs)_Scaling)_Di	scretes /	1
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			Single Station N	1ode E	Ethernet (Use Stati	on IP) N/A	



ISaGRAF Open

•ISaGRAF Open includes:

- ISaGRAF v5 editor
- SIXNET enhancements
- v3 features for backward compatibility to installed SIXNET RTU base
- Differences.pdf > C:\Program Files\SIXNET ISaGRAF
 Open\Documentation 5.1\Users Guide\English

•Based on the International Standard IEC 61131-3

• ISaGRAF supports all five programming languages:

- Sequential Function Chart
- Ladder Diagram
- Structured Text
- Instruction List
- Function Block Diagram
- (also supports Flow Chart)



ISaGRAF Open





IPM Controller

- Quick start for software programming that will work with any RTU
- Embedded Linux controller
- Shared IO database
- Supports a number of running applications
 - Alarming, Datalogging, custom C application, protocol conversion, web server





Main Summary

- 1) ISaGRAF Open Create and name new project
- 2) SIXNET Tool Kit Start project
- 3) Configure RTU
- 4) Export Tags To ISAGRAF Project
- 5) Develop simple program & Build (compile) ISAGRAF program
- 7) Load IPM Controller with Tool Kit
- 8) Load ISAGRAF Program with the Open Workbench
- 9) Load Tool Kit & ISaGRAF program in one step
- 10) Exercise program
- •Let's get started!!



- Run the Open Workbench
- File > New Project (name = PumpOne)
- •Name and select Template (ISaGRAF_RTU_Project)
- Save
- Step one complete!

Destination folder	25
C:\Program Files\SIXNET ISaGRAF Open\Proj	Browse
Name: PumpOne	
Name. If umporte	
Comment:	
Comment: Template: ISaGRAF_RTU_Project	

Proprietary

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- •Open Tool kit
- Start new project (File > New Project)
- Select Project Name
 - Default project location = C:\SIXNET Tools\Projects
- Save this will automatically lead into the RTU configuration
- Add RTU station to configuration
- •Configure station:
 - RTU Type
 - Setup ports
 - Add a virtual I/0
 - Add a DI module and Tag I/O (Tags = TurnOnMotor1 & Level)
 - Add a DO module and Tag I/O (Tag = Motor1)



Export Tags To ISAGRAF Project

Proprietary

- Goto File Menu > Export > I/O Definitions > ISAGRAF⁰
 - Select ISAGRAF Open
 - Browse to Project file: Location = C:\Program Files\SIXNET ISaGRAF
 Open\Projects\ISaGRAF 5.1\Prj
 - Select RTU
 - Finish

Note: View video to review process

File	Edit View Device Configure	Operation	is Tools	Panels Help				
B	New Project	Ctrl+N	4 4	🗛 😥 🙀 B			• 💣 🔝 🔚	2
Ê	Open Project	Ctrl+O	Status	Station Name	•	Station / lumber /	Station Type	Conn
	Save Project <u>A</u> s	Cm+5	ок	NewSta1		1	VT-IPM-1410	Not D
	Import	•						
	Export	•	I/O I	Definitions to 📣		Another S	tation	
	Print	•	Regi	stration Info		ISaGRAF.	u.	
	Print Preview	•	I/O '	Transfers	-	Citect (Sxi	Direct Driver)	



Develop program and build (compile)

- •Open project
- •From Resource window right click on Programs and Add Program Type (use FBD)
- Open FBD program
- •Select F3, or the Function block symbol and add AND block
- •Select F2, or Variable symbol and add variables accordingly
- •Select F4 function to connect variable to function block
- •Save
- Compile



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Load Tool Kit configuration first to be sure the port settings are correct

- •By default all IPM stations are 10.1.0.1
- •Tools > Device Menu > Select
 - Choose Serial or Ethernet

•Ok

•Operations Menu > Load > Basic Settings



Load ISAGRAF Program with the Open Workbench

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- Goto Tools Menu (or Project Tree View)
 > Communication Link Setup
- Select Device > Single Station
- Select "use project file settings" Browse to project file

•Ok

Note: The IP address or serial port settings are found in the Tool Kit project file automatically. Otherwise, select "Use these settings" for manual purposes.

See next slide to complete the load





Load ISAGRAF Program

- From Main Workbench window select Debug Menu > Download
- Select Resource (Check box)
- Save on target after download
- Start after download
- Download

Program is now loaded and running in RTU!

✓SIXNET_RTU_CFG:	1:Res1 (* Resource Numl	ber 1 *)
conte Cataval	Colora All 1	Thursday All
oggle Select	Select All	Unselect All



Load Tool Kit & ISaGRAF program in one

step

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- From the Tool Kit setup "Files to Load" in RTU configuration
- From the ISaGRAF Tab Check "Load an ISaGRAF program"
- •Run time version RTU
- •Select project: appli.X6M
- •To Load: Operation Menu > Load > Advanced Selected, or Predefined files

🗹 Load an ISaGR/	AF program:
Run time version:	RTU
Project	C:\Program Files\AF Open\Projects\ISaGRAF 5.1\Prj\PumpOne\ISA3\ApI\RES1\appli.X6M
Configuration	



Exercise program

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•From the SIXNET Tool Kit run Test I/O to station

- Test IO will work if Virtual Input modules are used. If Onboard Inputs are used a the RTU will need to have a wired input or use the Workbench debug lock feature.
- Make sure the device menu is setup accordingly
- •Operations Test I/O
- •Turn on DI Tags "TurnOnMotor" & "Level"
- •Result = DO Tag "Motor1" will turn On.



Test program using the ISaGRAF Debugger

- •Run ISAGRAF Debugger: Debug > Debug Target
- Open the program
- Double click on Input Tag
- Select Lock
- •Double click on Tag again
- •Select "True"
- •Do this for both Inputs & Motor1 will turn ON.

