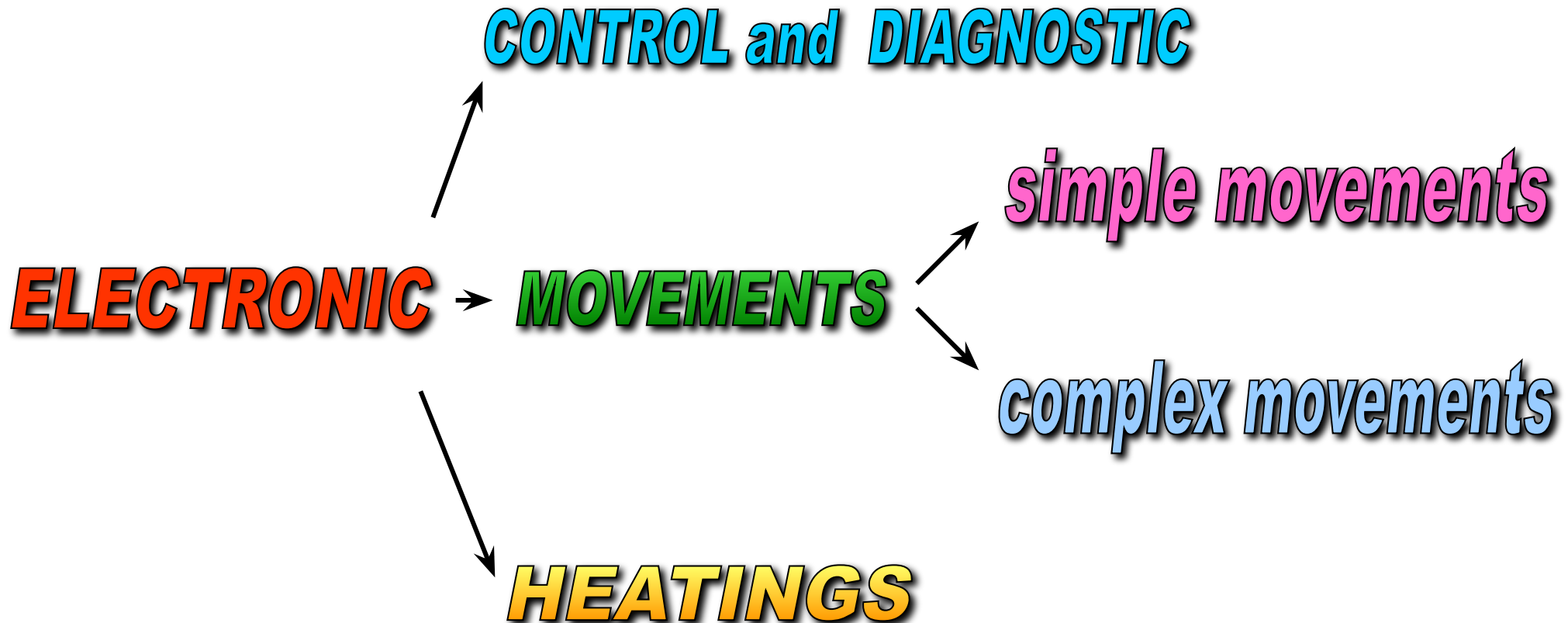


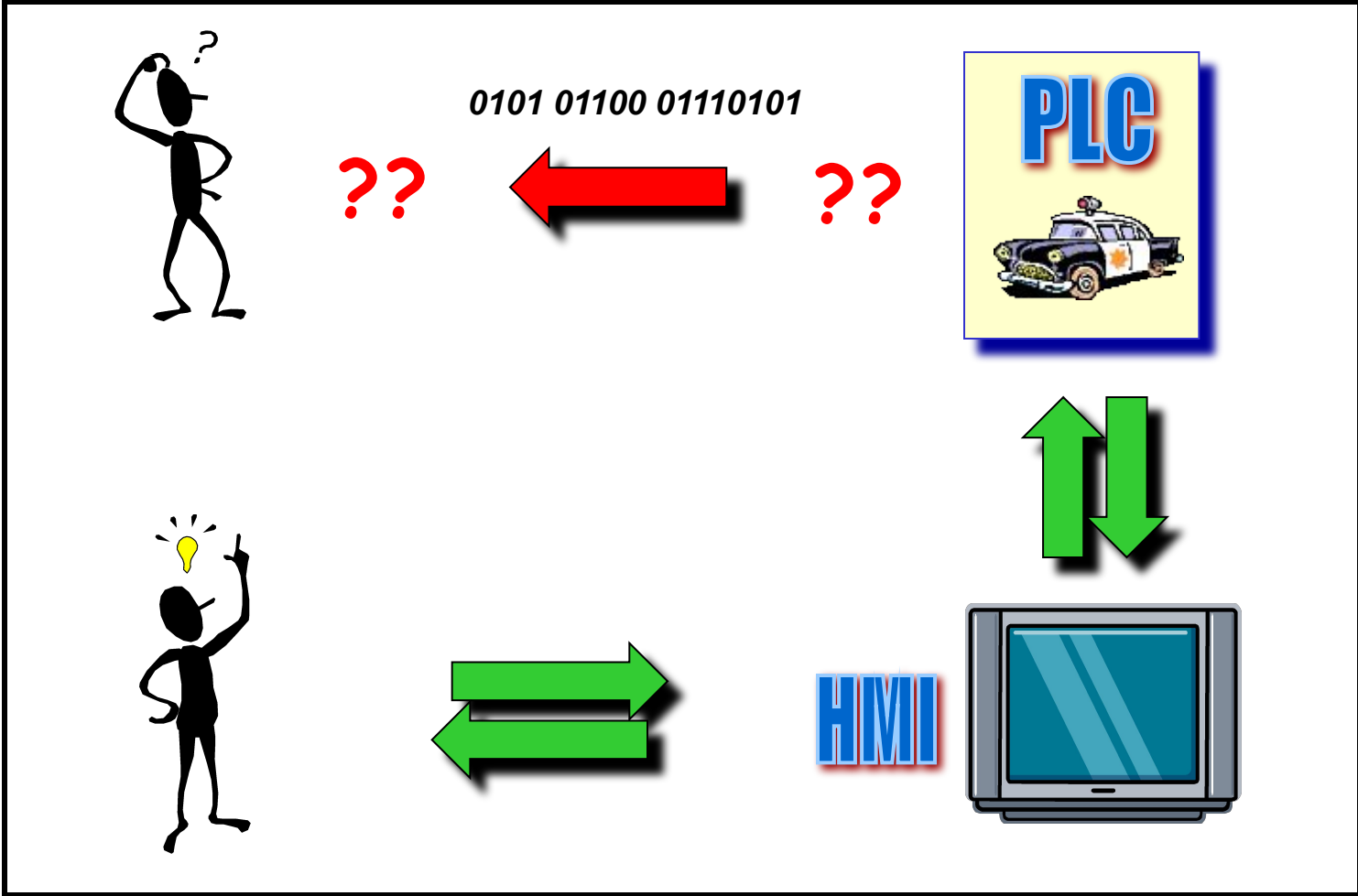
SFR Evo ELECTRIC LAYOUT AND ELECTRONIC MANAGEMENT



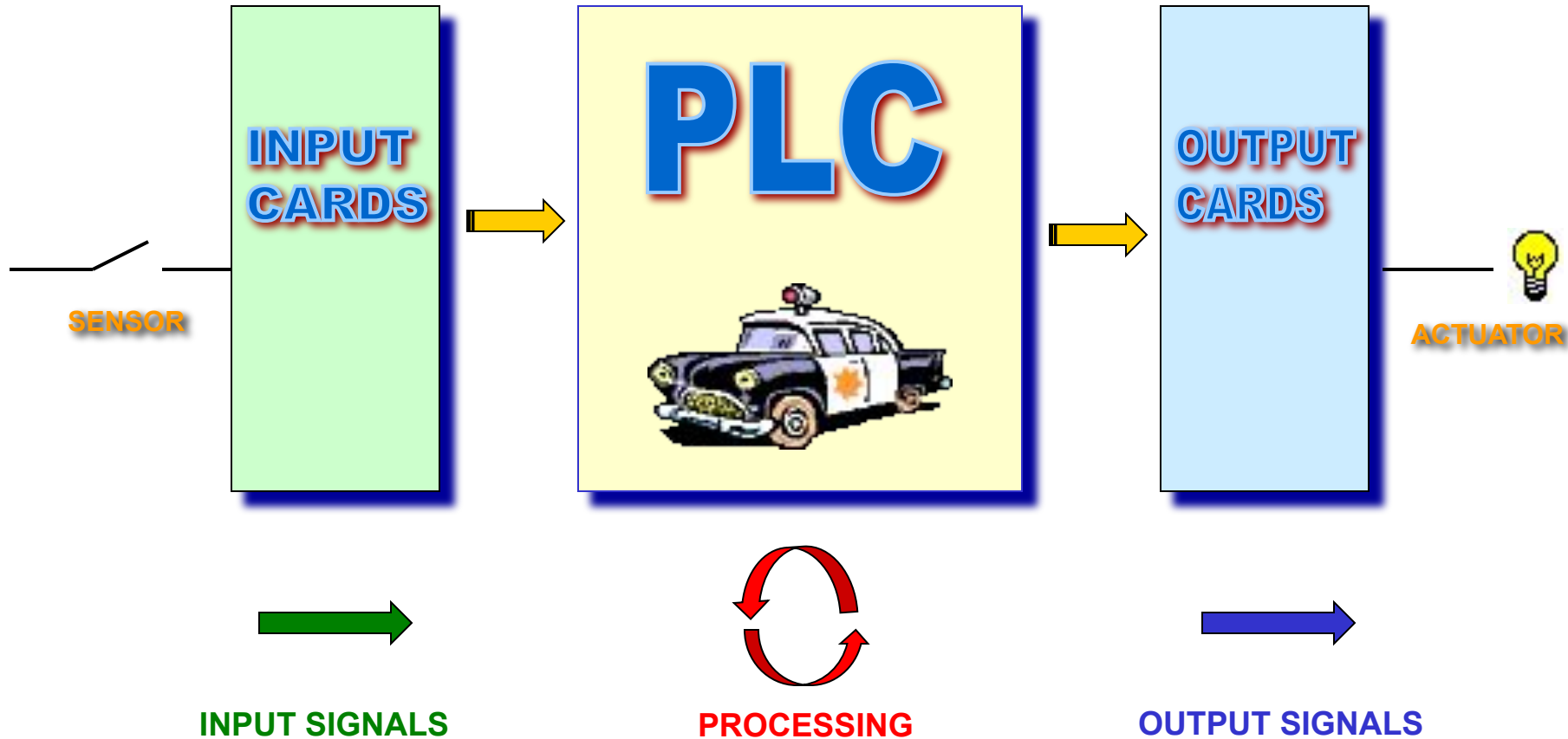
ELECTRONIC SYSTEM PURPOSE



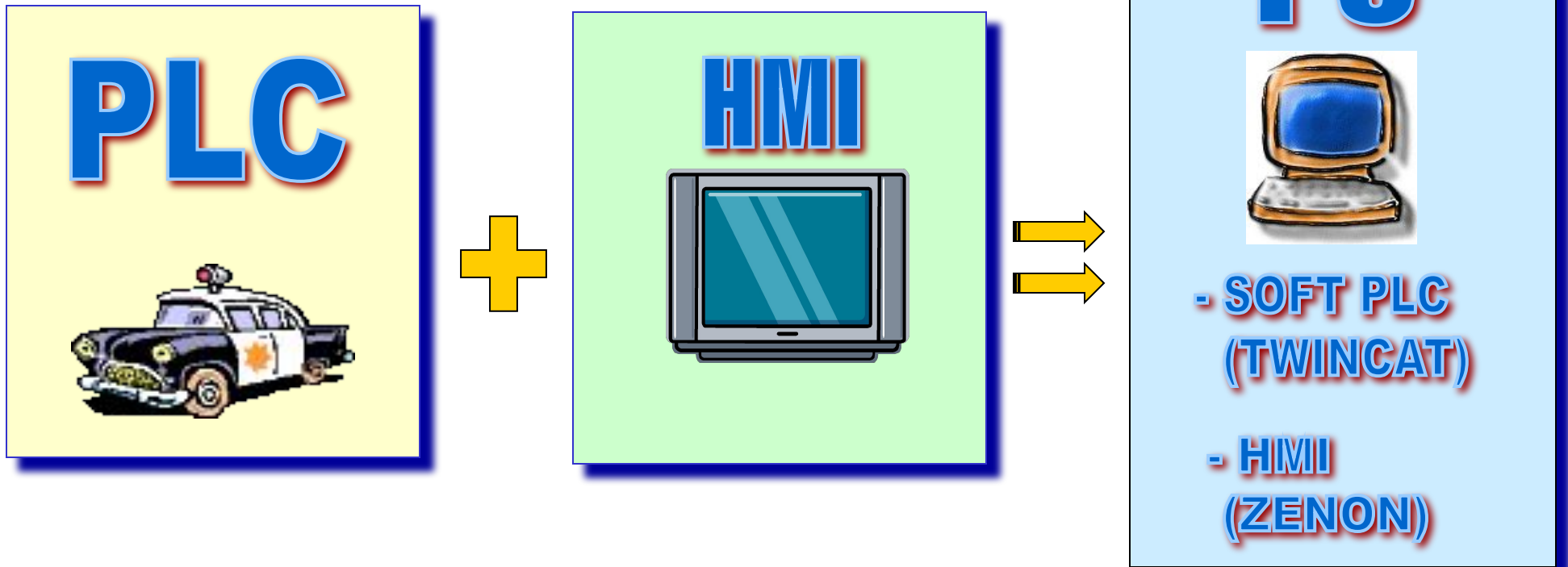
OPERATOR INTERFACE PURPOSE



PLC - Programmable Logic Controller



PC - Personal Computer



PC

Windows XP

SOFTWARE

SUPERVISOR

SOFT PLC

FIRMWARE

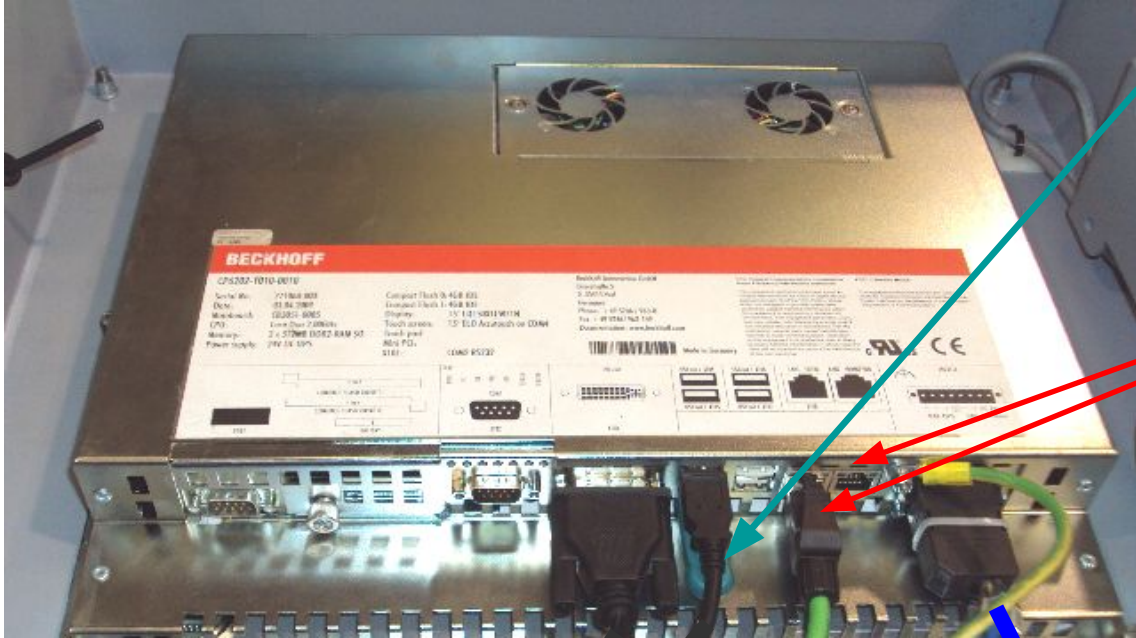
HMI
and
MACHINE
MANAGEMENT

HARDWARE

BOARDS
CANopen
(RS422)
ETHERCAT
PROFIBUS
USB, DVI

I/O
SERIAL
LINES
PC

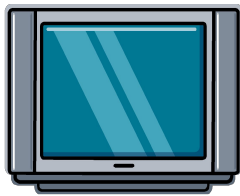
LAYOUT PANEL PC



DONGLE ZENON (USB)

ETHERNET

TOUCH SCREEN



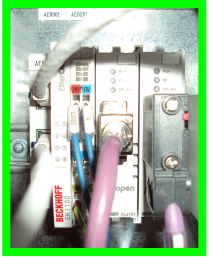
DVI

USB

ETHERCAT

24 Vdc

UPS



EK1100 - BRIDGE

LAYOUT BRIDGE EK1100

INTELLIGENT
SOCKETS

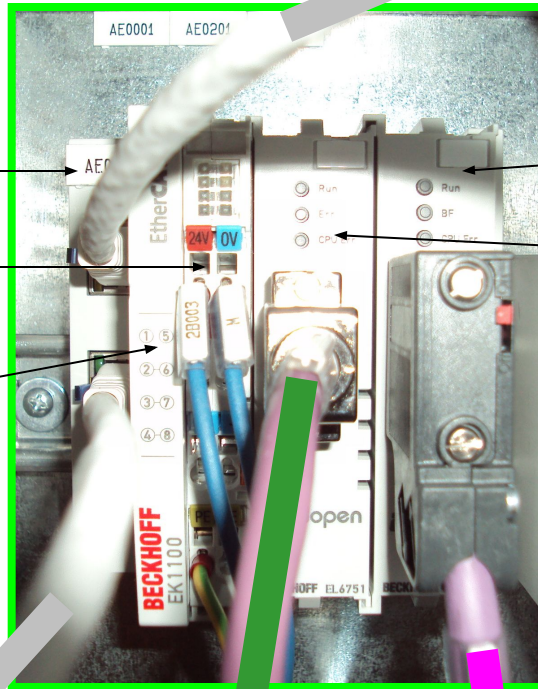


EK1100 - BRIDGE

SLAVE
ETHERCAT

SUPPLY 24V

BASE MODULE
EK1100



ETHERCAT

MASTER
PROFIBUS

MASTER
CANOpen

CANOpen

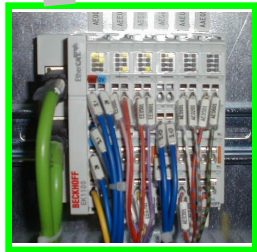
PROFIBUS



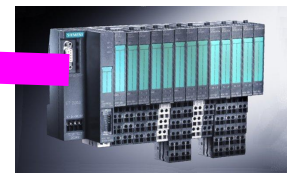
PC
(MASTER
ETHERCAT)

EK1100

ETHERCAT



I/O MODULES



PWRC08



SERIAL LINES



PROFIBUS serial line

It allows communication between PLC and the nodes (slave), i.e. PLC with ET200S modules.

Ethercat serial line

Fast ethernet without communication dead times. It allows communication between PC (Master) and I/O modules EK1100 and the Intelligent Sockets (slave).

CANopen serial line

or

RS422 serial line

It allows communication between PC and PWRC08 power cards.

It allows communication between PC and IRAZ24 power cards.

USB & DVI serial line

It allows communication between PC and the HMI panel and modem.

NODES

Electronic units dedicated to specific tasks and areas of the machine. Identified by an address. Each node is connected via serial line. There are different kinds of nodes:

PROFIBUS node

- I/O MODULES, digital and analogue (slave)
- BRIDGE EK1100 (Master)
- DRIVES (slave)

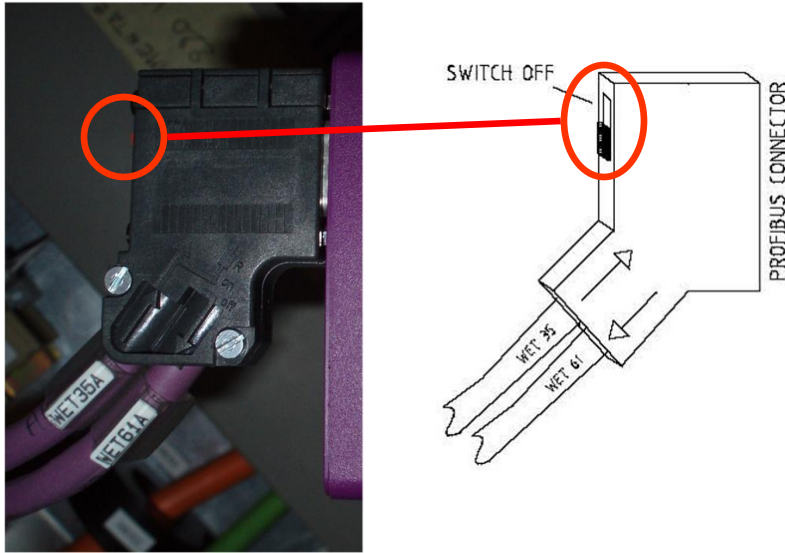
Ethercat node

- PC (Master)
- BRIDGE EK1100 (slave)
- I/O EK1100 (slave)
- INTELLIGENT SOCKETS (slave)

CANbus node

- PWRC08 (slave)
- BRIDGE EK1100 (Master)

NODES ADDRESSES

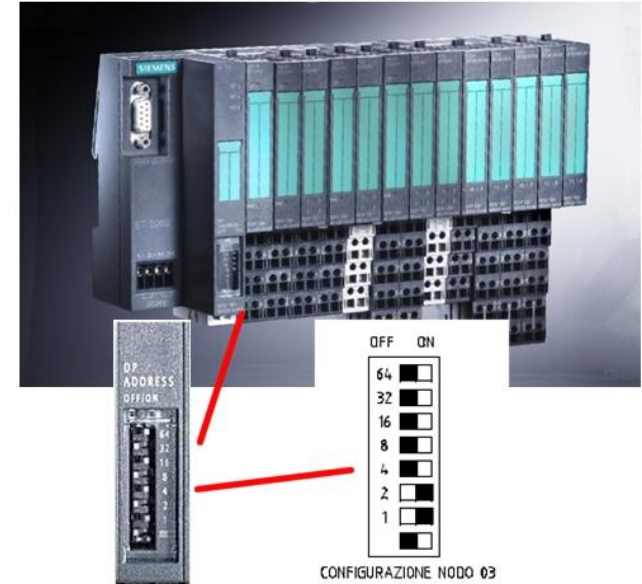


PROFIBUS connector selector

Can have 2 positions:

ON – for terminal positions (beginning and end of the serial line)

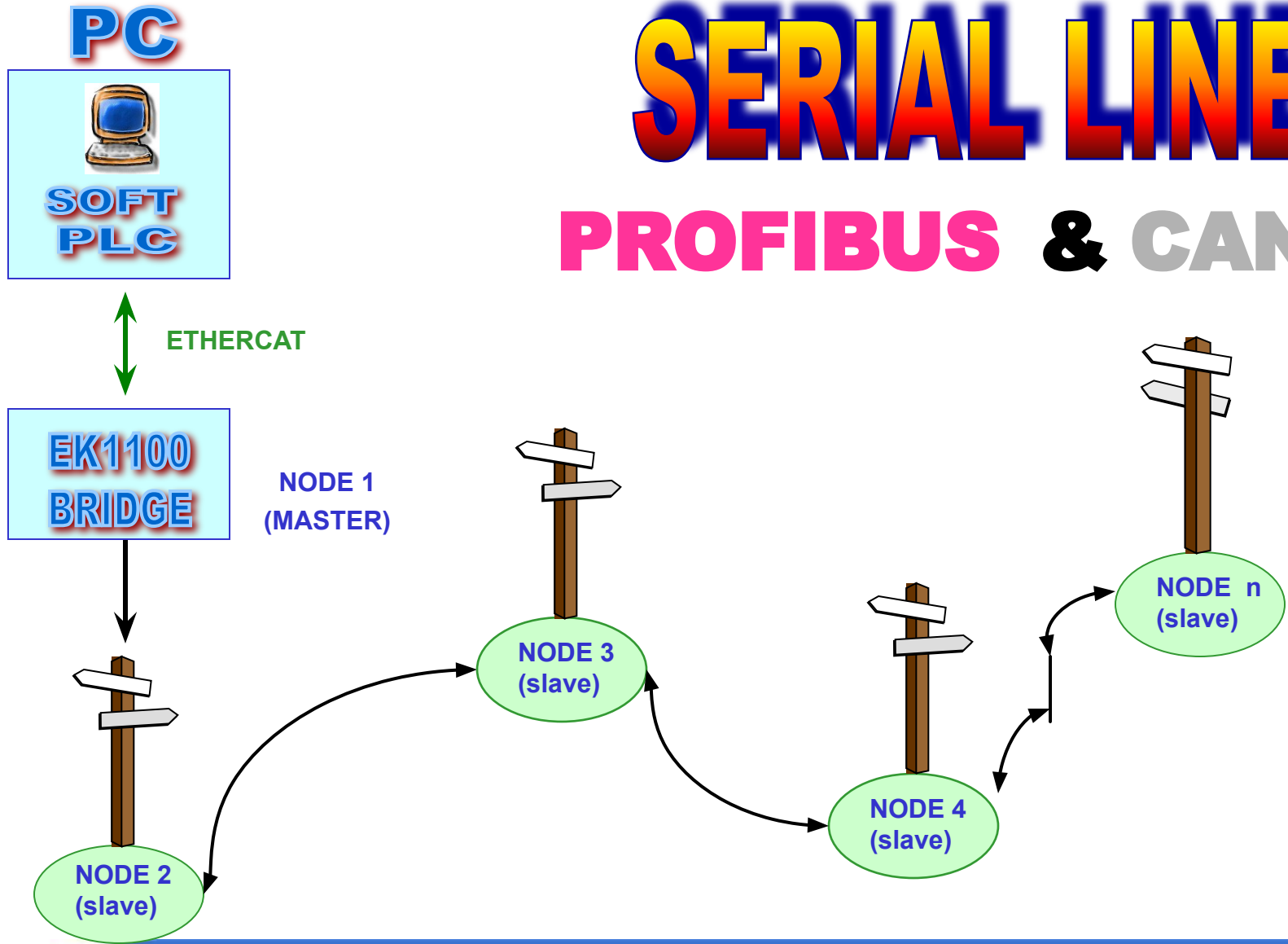
OFF – for the intermediate positions (passer-by)



Setting PROFIBUS node address (dip-switches)

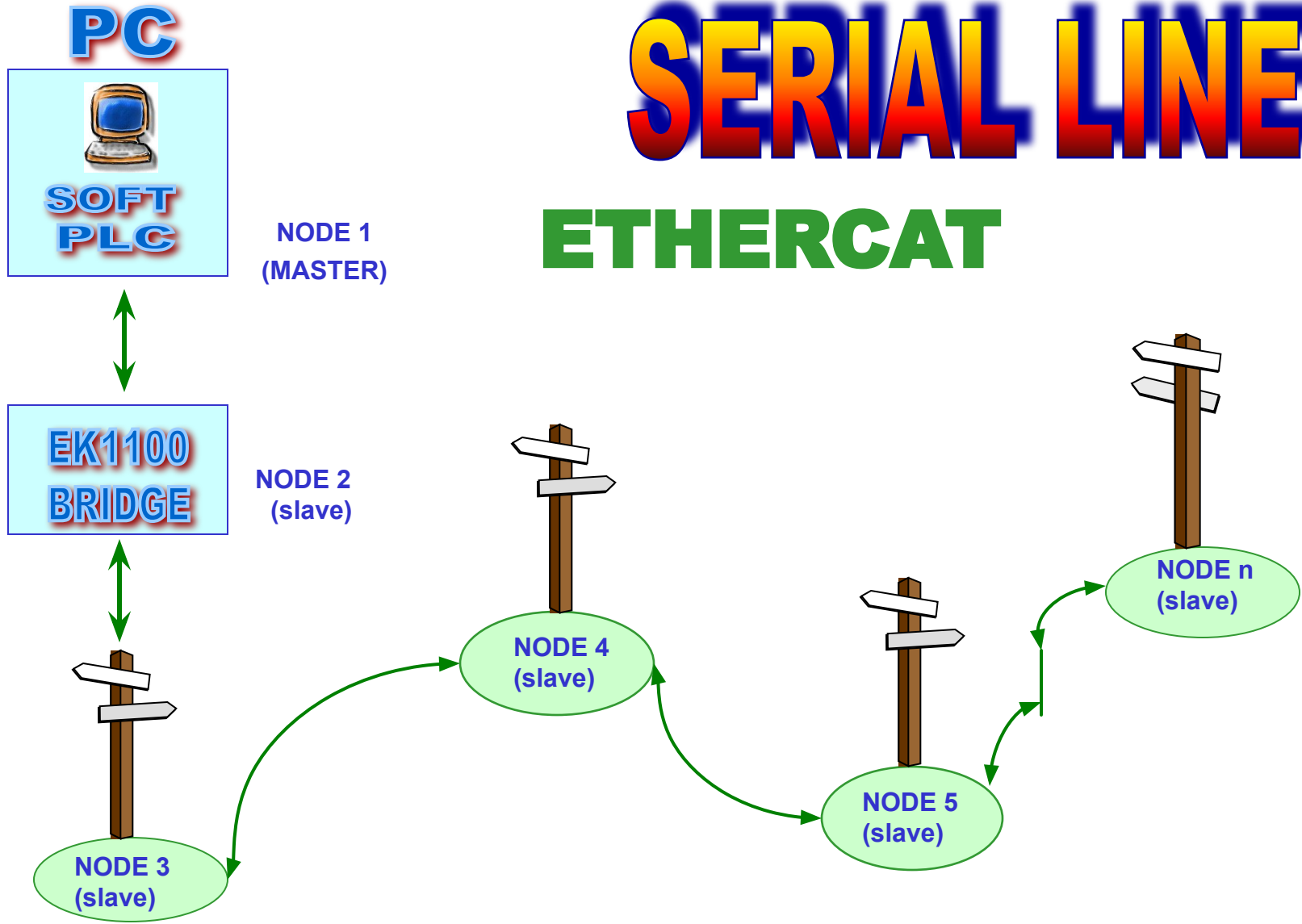
SERIAL LINE

PROFIBUS & CANopen



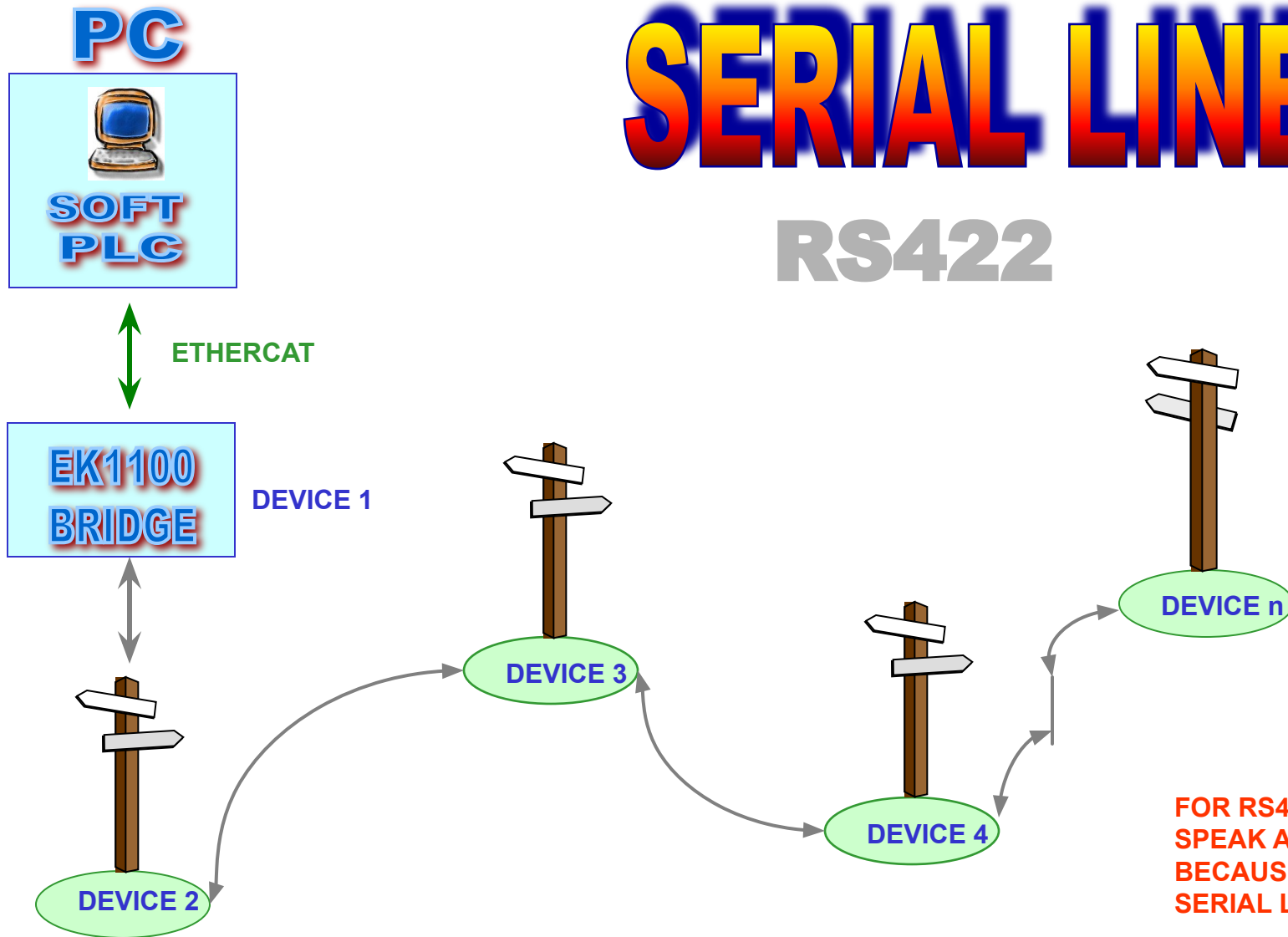
SERIAL LINE

ETHERCAT



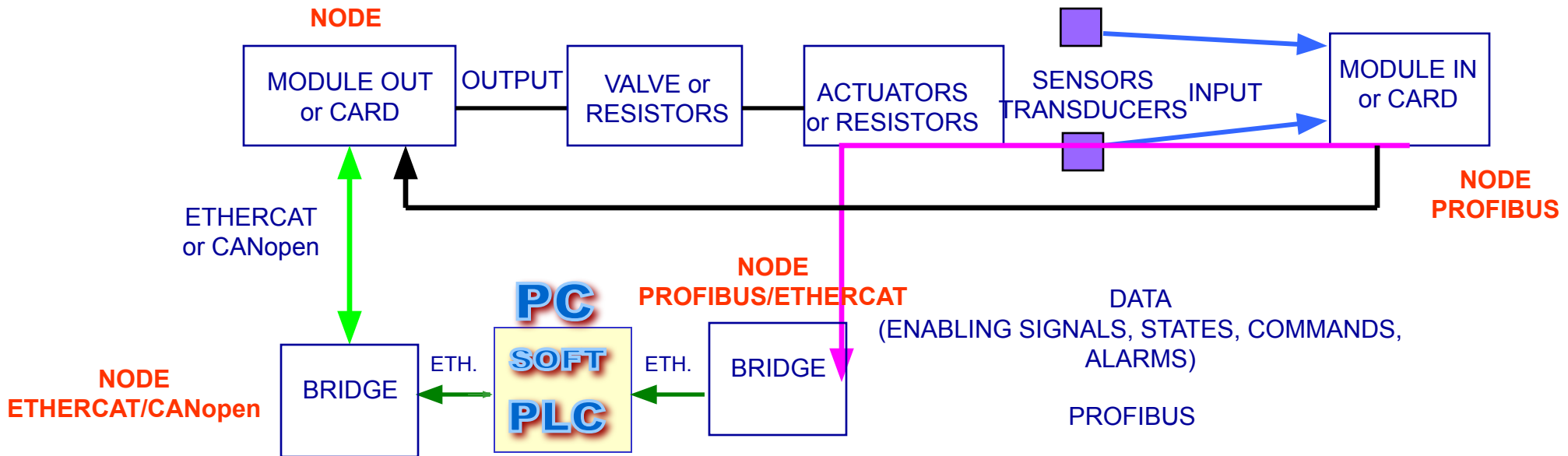
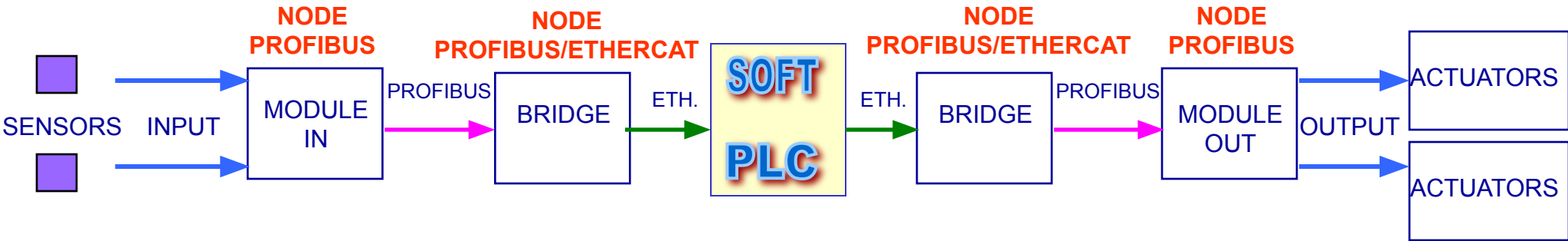
SERIAL LINE

RS422



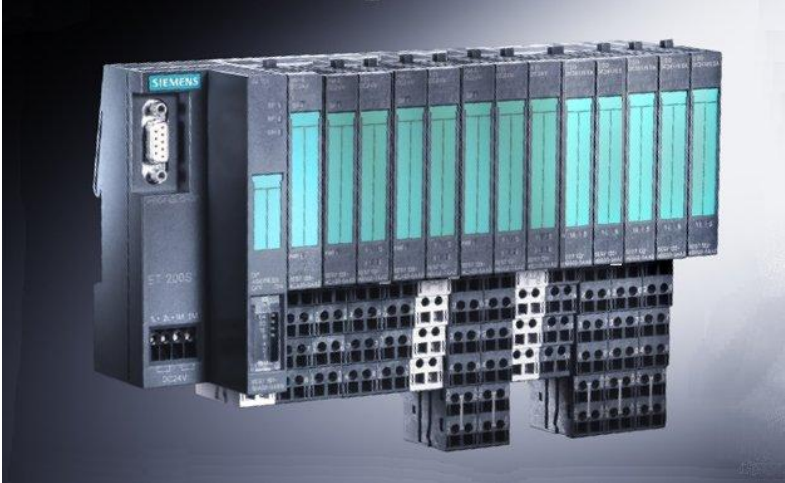
FOR RS422 WE CANNOT
SPEAK ABOUT NODES
BECAUSE IT IS A PURE
SERIAL LINE

NODES



SIEMENS ET 200S I/O MODULES

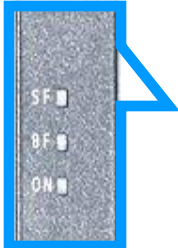
Connector for PROFIBUS serial line



DIAGNOSTIC LEDs:

- ON ON:** internal module correctly supplied
- ON OFF:** internal module not supplied
- BF ON:** failed communication with the CPU
- BF OFF:** communication OK
- SF ON:** failed communication between modules
- SF OFF:** no errors

- LED SF
- LED BF
- LED ON



- DI: Digital Input
- DO: Digital Output
- AI: Analogic Input
- AO: Analogic Output

- E (Engang) xxxx: Input
- A (Ausgang) yyyy: Output



24 Vdc supply

ADDRESS setting of the module (and of the node)



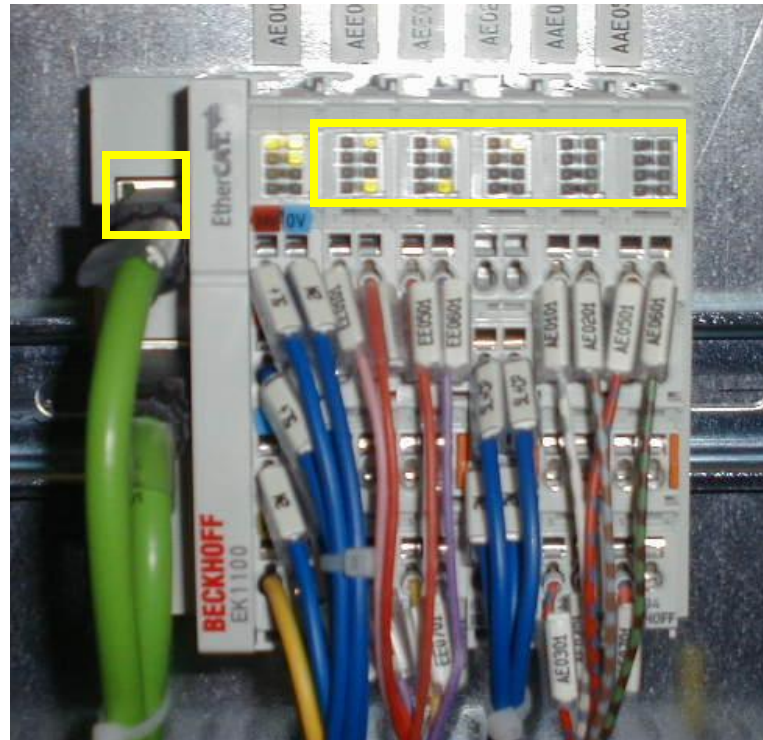
Terminal box for input and output signals

I/O MODULES EK1100

Supply 24 Vdc

 I/O ENABLED

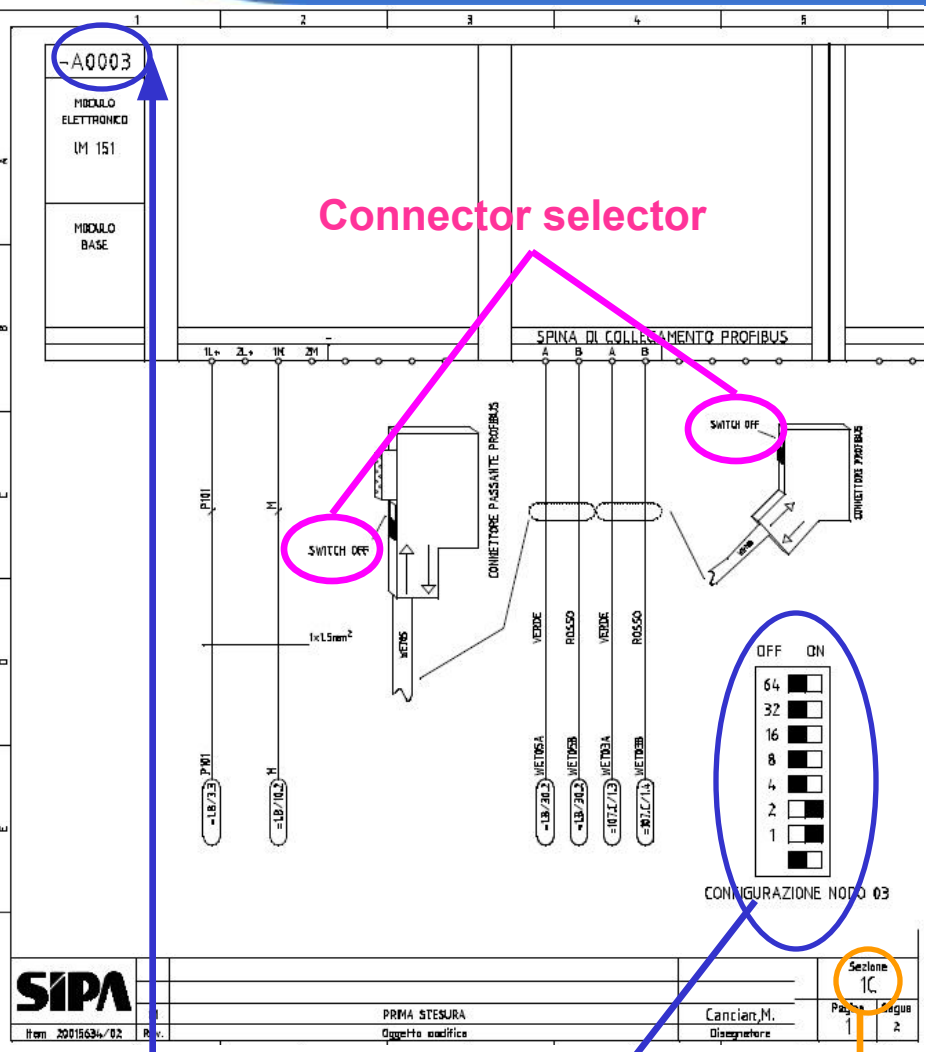
Network connection
status



AEE or EE: digital input
AAE or AA: digital output
ARE: analogue input
ARA: analogue output

Serial connection
ETHERCAT

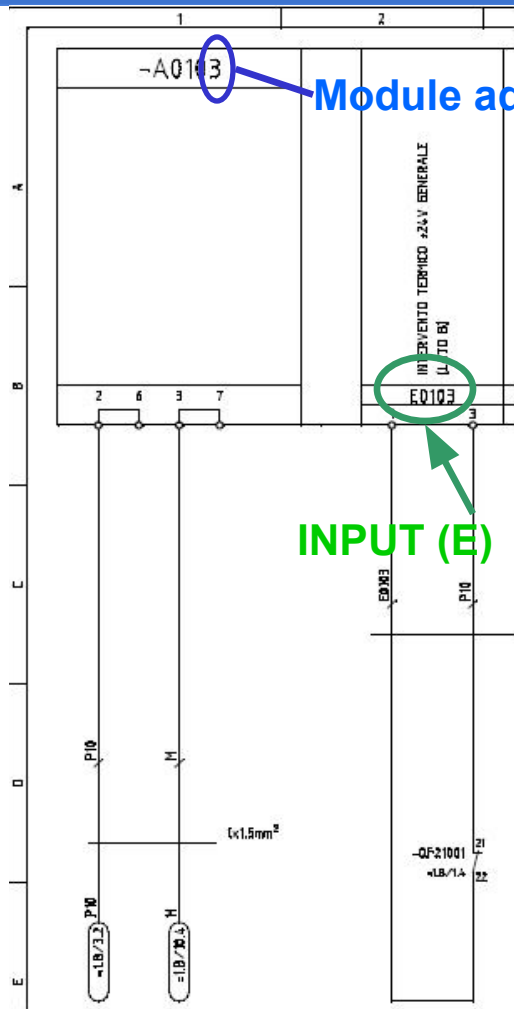
Terminal box for
input and output
signals



Connector selector

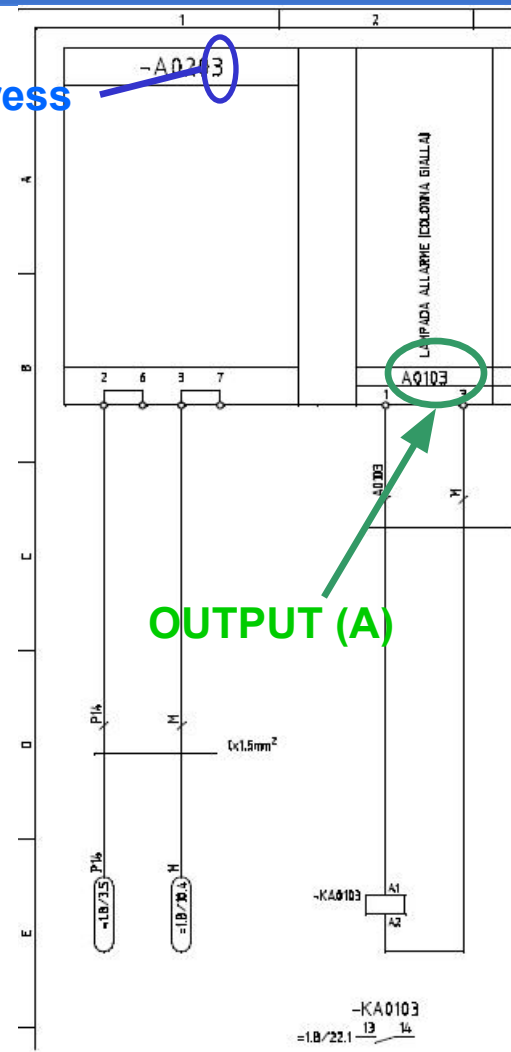
Module address

I/O section electric diagrams



Module address

INPUT (E)



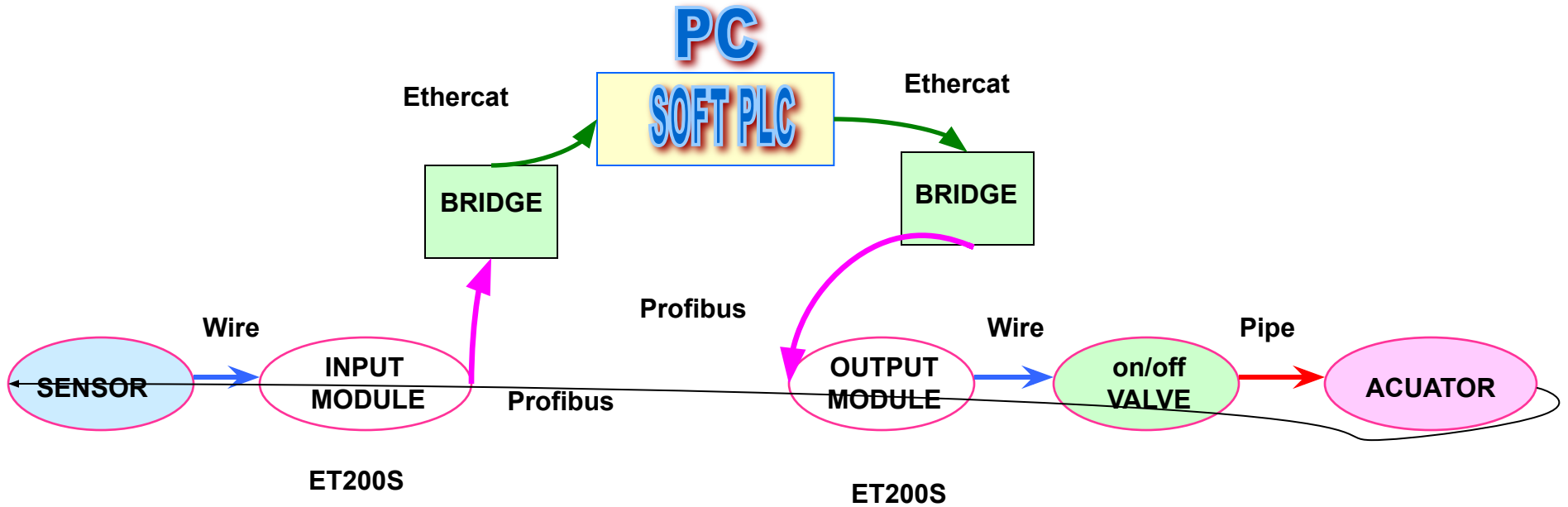
OUTPUT (A)

KIND OF MOVEMENTS

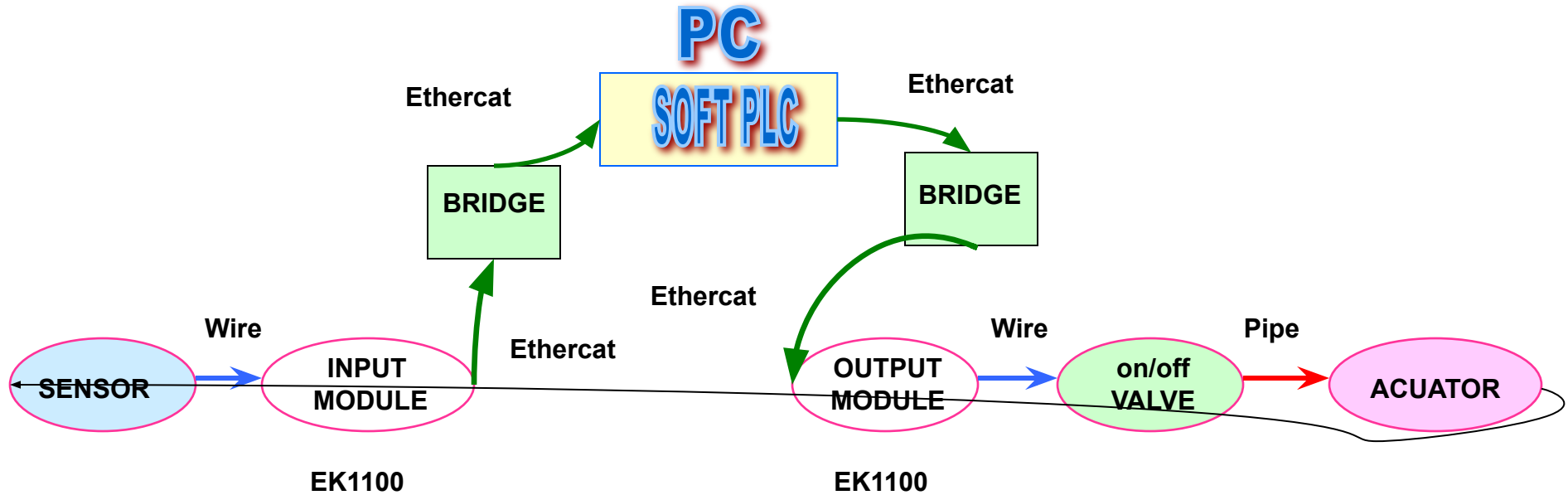
→ **SIMPLE** with **ON/OFF VALVE** and **ON/OFF SENSOR**

→ **COMPLEX** with **DRIVE** and **TRANSDUCER (linear or rotary)**

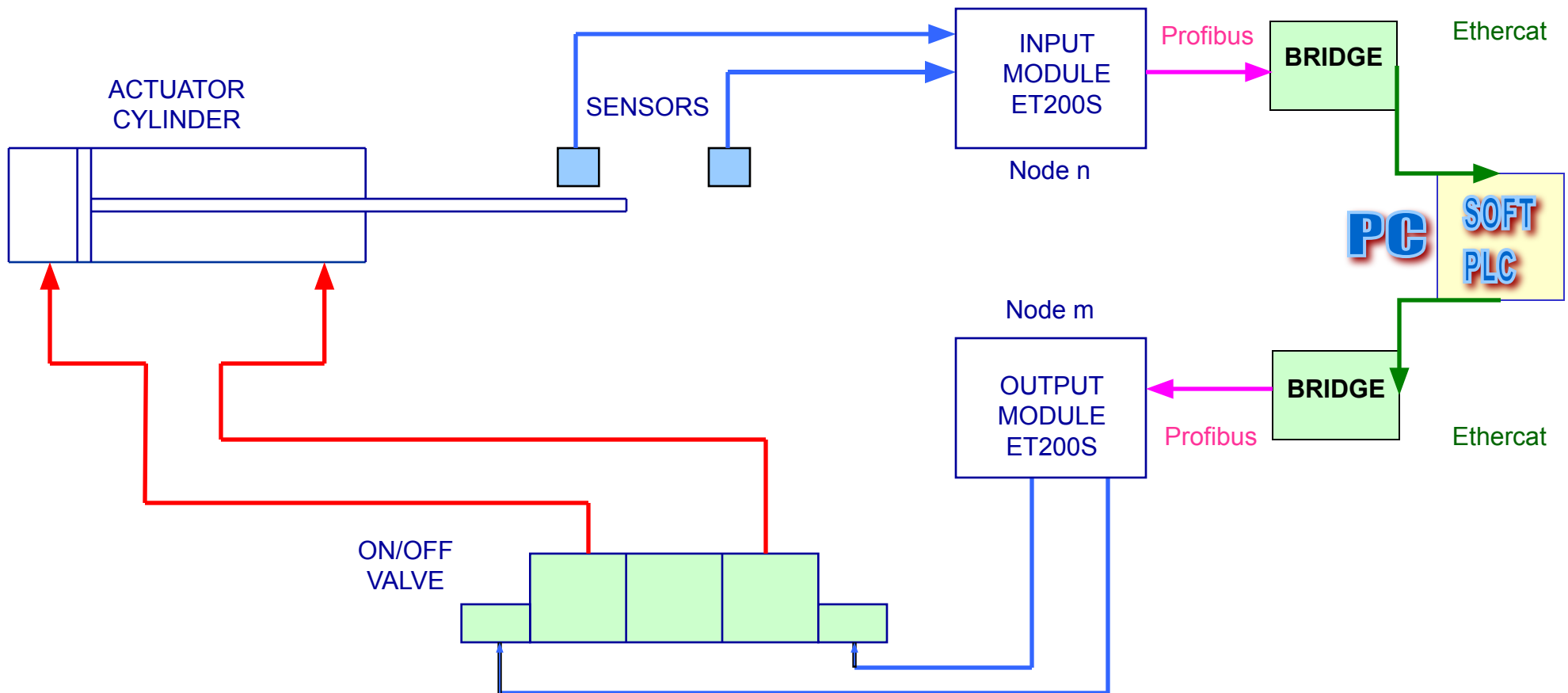
SIMPLE MOVEMENTS (1)



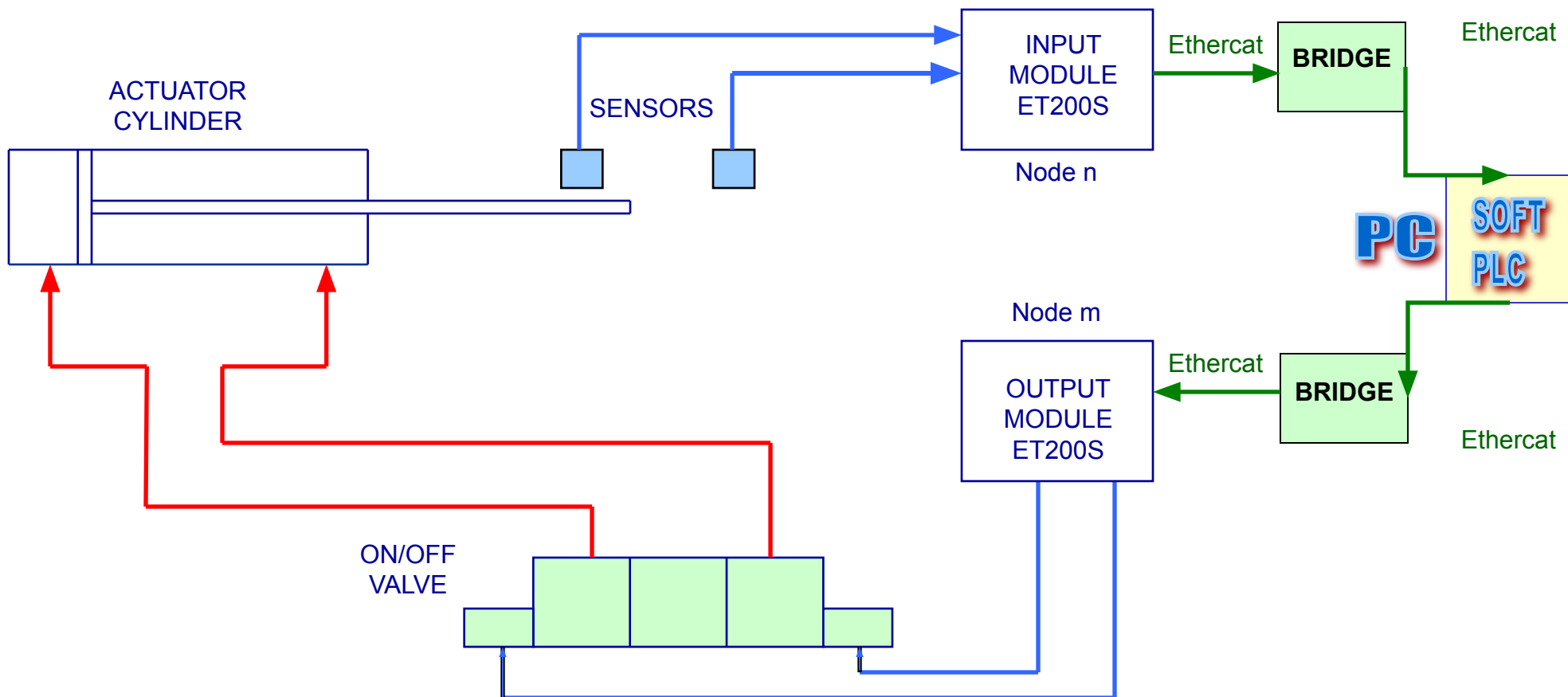
SIMPLE MOVEMENTS (2)



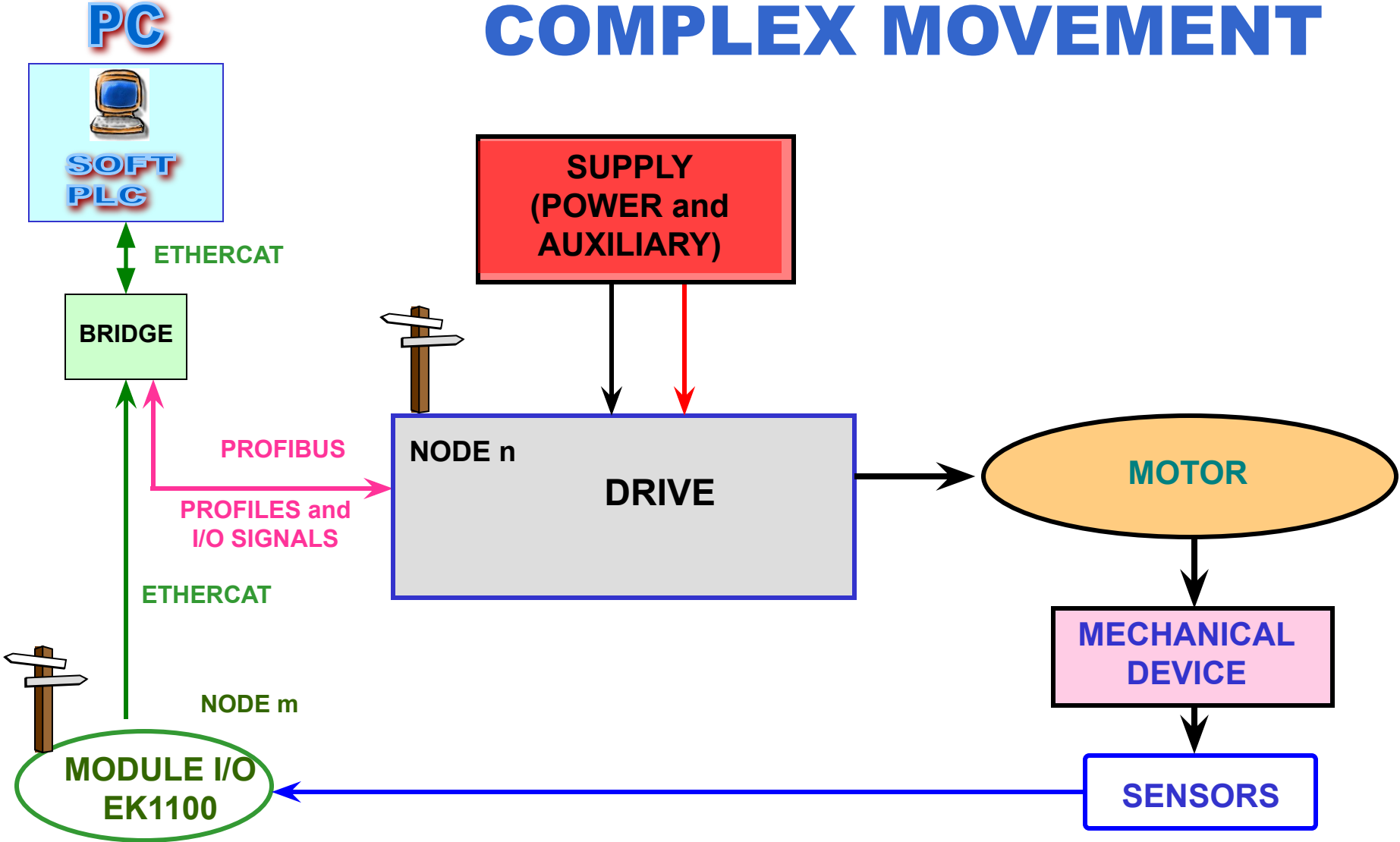
SIMPLE MOVEMENTS WITH ON/OFF SENSORS (1)



SIMPLE MOVEMENTS WITH ON/OFF SENSORS (2)



COMPLEX MOVEMENT



ELECTRONIC COMPONENTS



PANEL PC



LOGIC CONTROL (SOFT PLC)
ELECTRONIC CAMS GENERATOR
HMI



CONTROL TECHNIQUES



DRIVE



IP2001



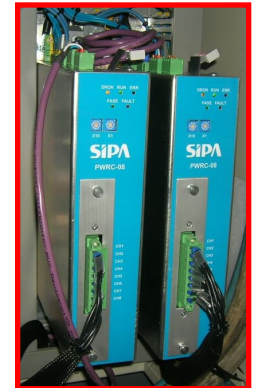
INTELLIGENT SOCKETS



PWRC08 (IRAZ24)



POWER CARD



ELECTRONIC MANAGEMENT OF THE BLOWING WHEEL



ELECTRONIC CAM GENERATOR: PC has the function, thanks to the implementation of a dedicated software, to create virtual cams. The function is similar to a mechanical cam shaft but these are electronic and programmable. At every revolution of the blowing wheel, these cams send the enabling signals to the intelligent sockets through the Ethercat serial line in precise and fixed (but programmable) angular positions of the blowing wheel.



INTELLIGENT SOCKETS: these IP2001 electronic devices are located on every blowing press and receive the signals from I/O Ethercat modules EK1100. Their function is to enable the valves related to blowing (seals, blowing, compensation, ...). In this configuration are seen as digital output modules (slave) and own 8 outputs. The module self addresses automatically. The cards are supplied with 24Vdc.

ELECTRONIC MANAGEMENT OF THE BLOWING WHEEL



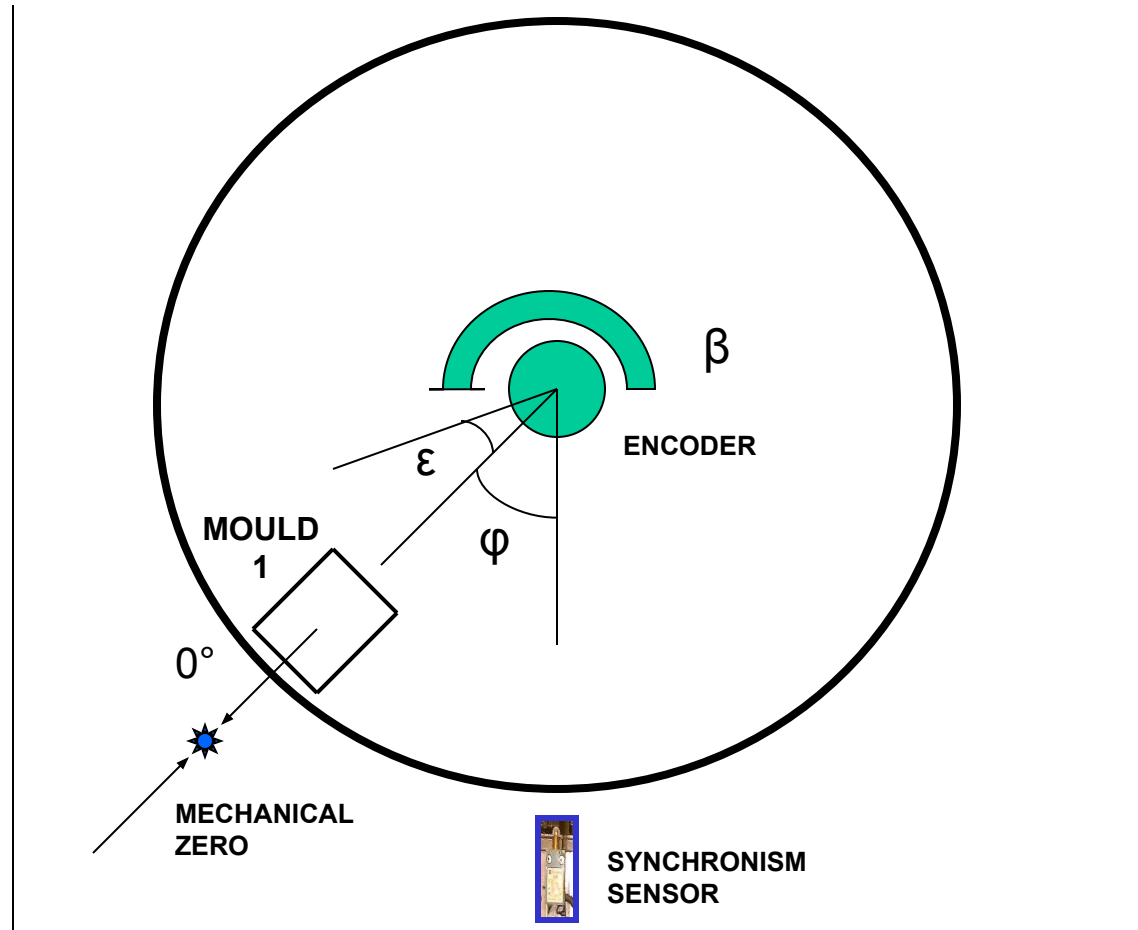
ABSOLUTE ENCODER: electromechanical device that converts the angular position of its rotating axis in electric numeric signals. The output electric signals codify the exact instant position of the rotor in respect of the body; so that, in any moment, an adequate decodifying circuit can decode and show the angular position of the axis. The data referring to the axis movement (direction, speed, acceleration) are calculated by processing its absolute position in time. It is used in the SFR machine to determine the angular position in any moment of the mould 1 (and consequently of the other moulds). The signals of the encoder are input of the EK1100 module. Information are not lost in case of powering off, but it is requested a setup procedure for the collimation between the logic zero and the machine zero.



SYNCHRONISM SENSOR: it verifies at every revolution of the blowing wheel the synchronization between the mechanical zero and the electronic zero of the mould 1, that is if every time the mould 1 passes in front of a fixed position of the machine frame (mechanical zero), the encoder reads a value of 0° (electronic zero).

ELECTRONIC MANAGEMENT OF THE BLOWING WHEEL

- β = actual angle of the mould 1 read by the encoder
- ε = possible difference of β from 0° (or 360°)
- If ε is different from 0, it is needed to set the correction (offset) in the electronic cams generator so as to have $\beta = 0^\circ$
- φ = angle (fixed value) for the synchronism control between the mechanical zero and the electronic one



ELECTRONIC MANAGEMENT OF THE BLOWING WHEEL

ENCODER

CAM GENERATOR

SOFT PLC



+



+



EK1100



OUTPUT

INTELLIGENT SOCKETS

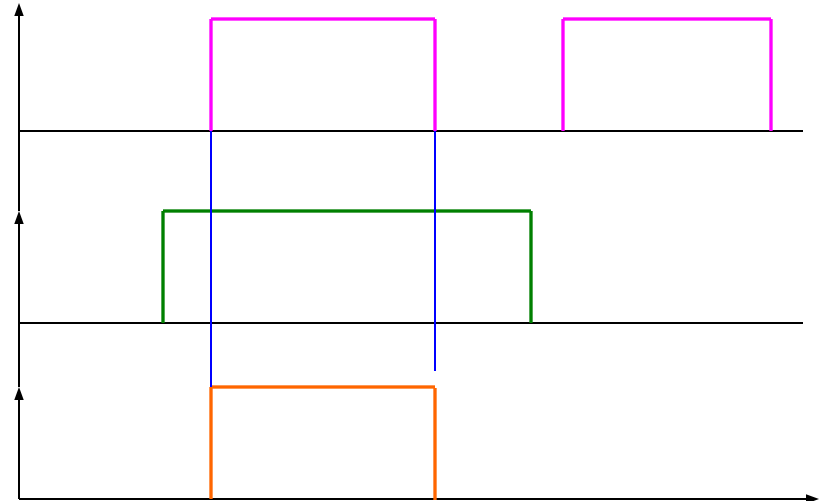


MOLDS

ELECTRONIC CAM

ENABLING FROM PLC

OUTPUT



MOTOR DRIVING

CONTROL + DRIVE

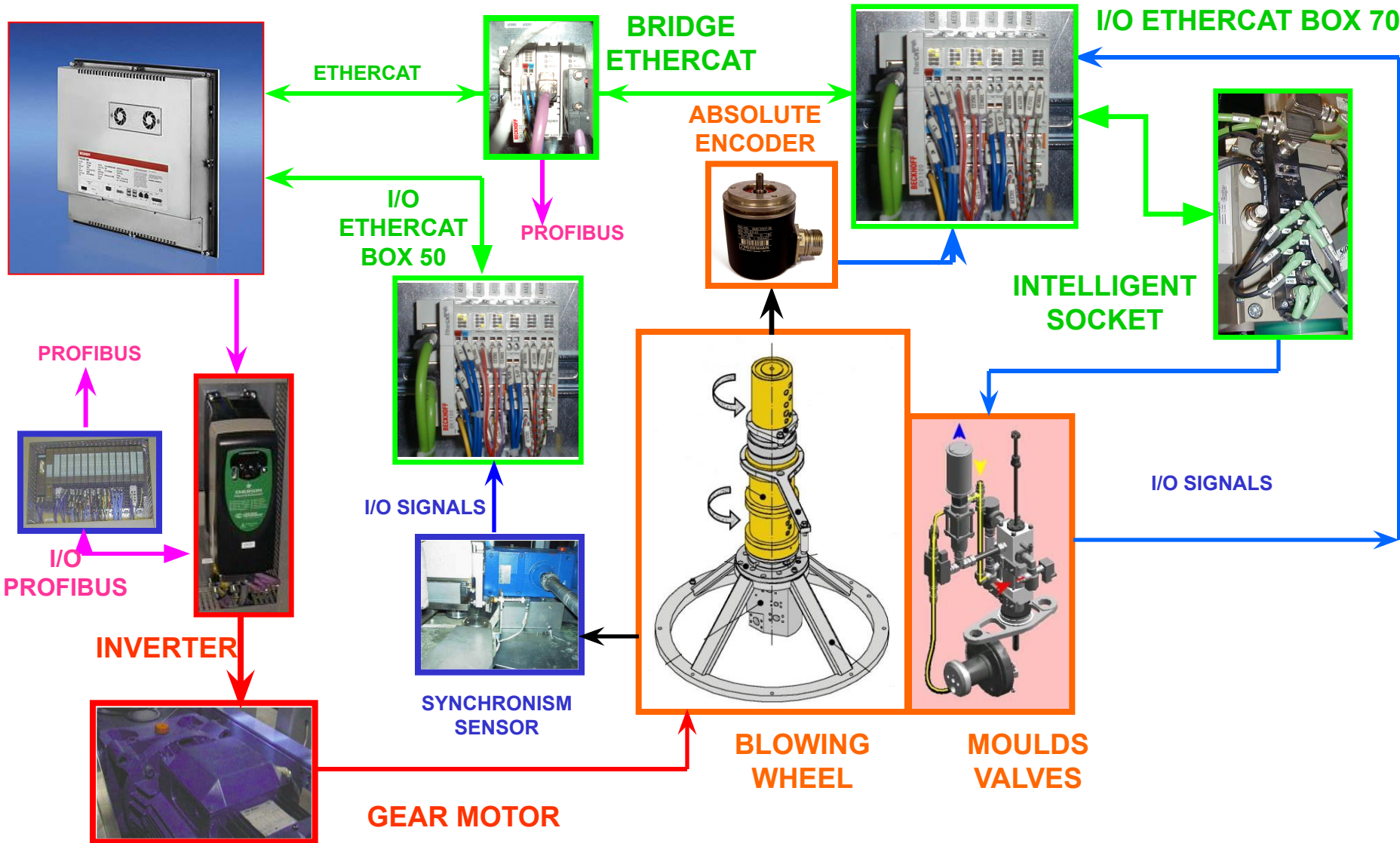


INVERTER + GEAR MOTOR



ELECTRONIC MANAGEMENT

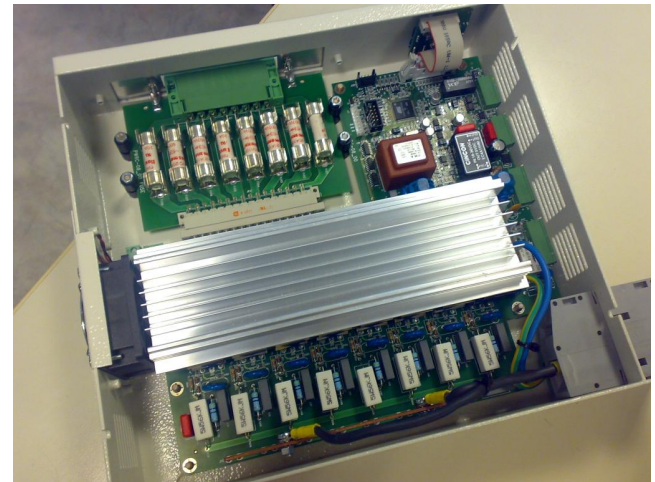
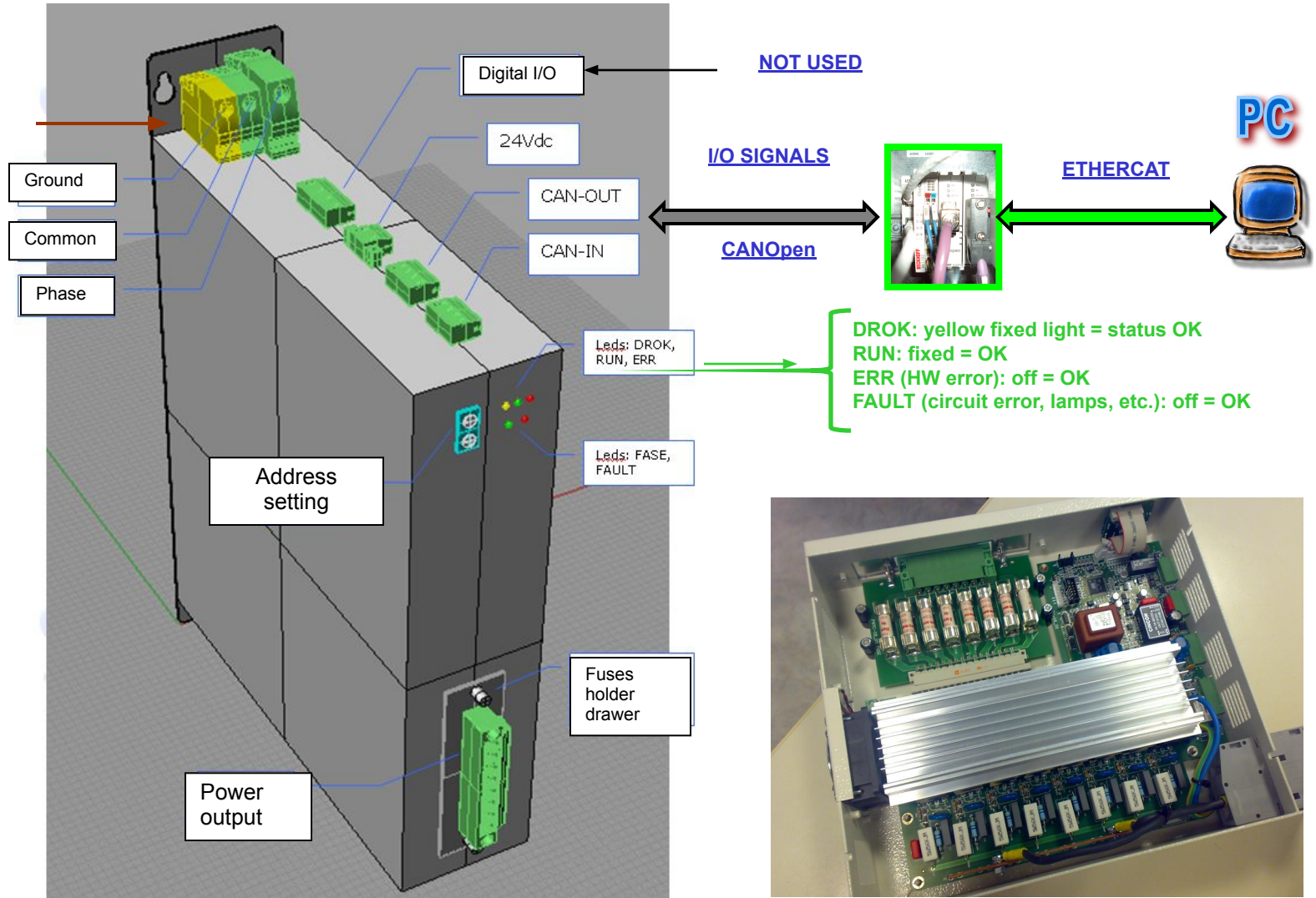
PC



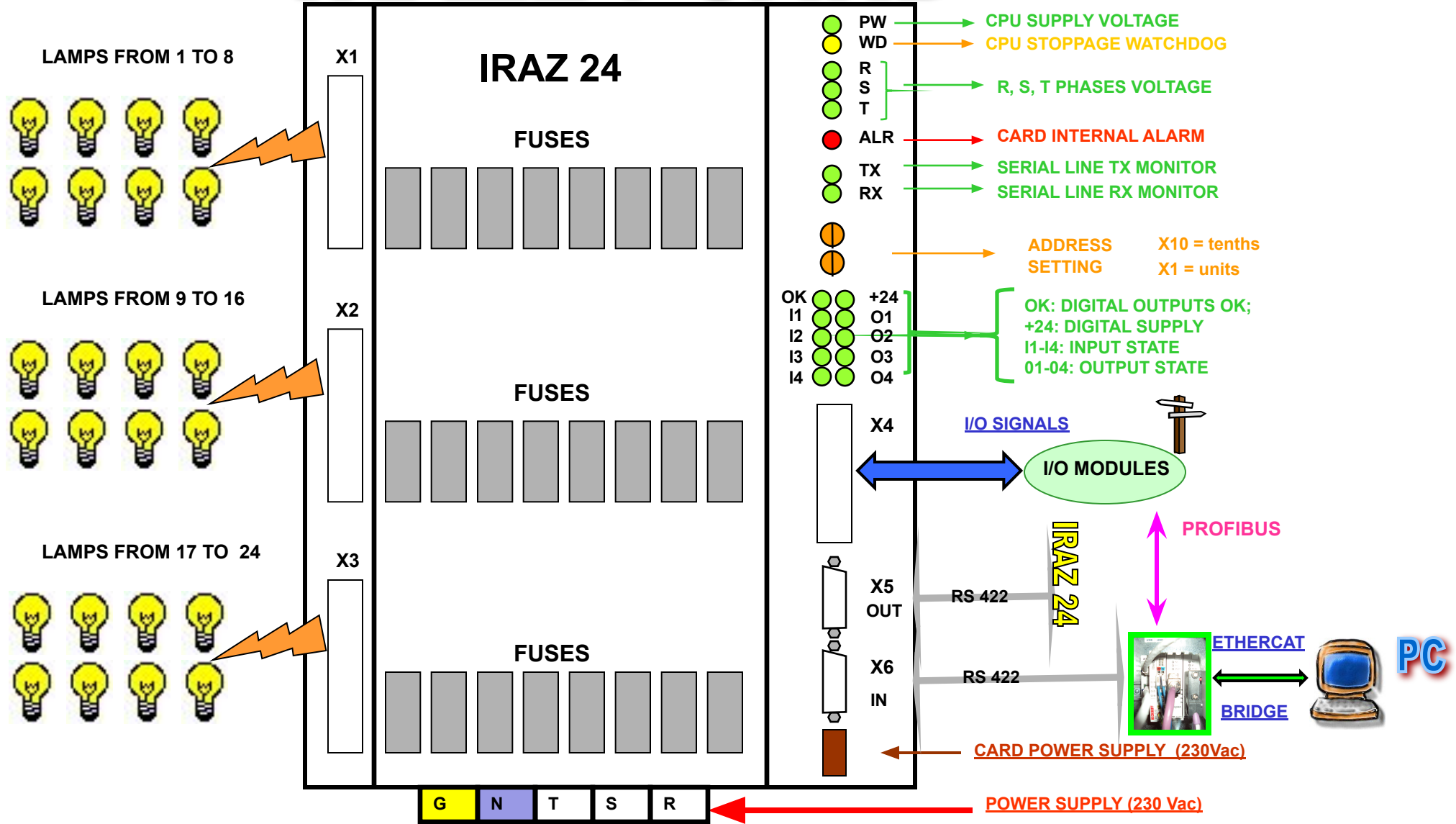
PWRC08

CARD SUPPLY (230Vac)

SINGLE PHASE VOLTAGE

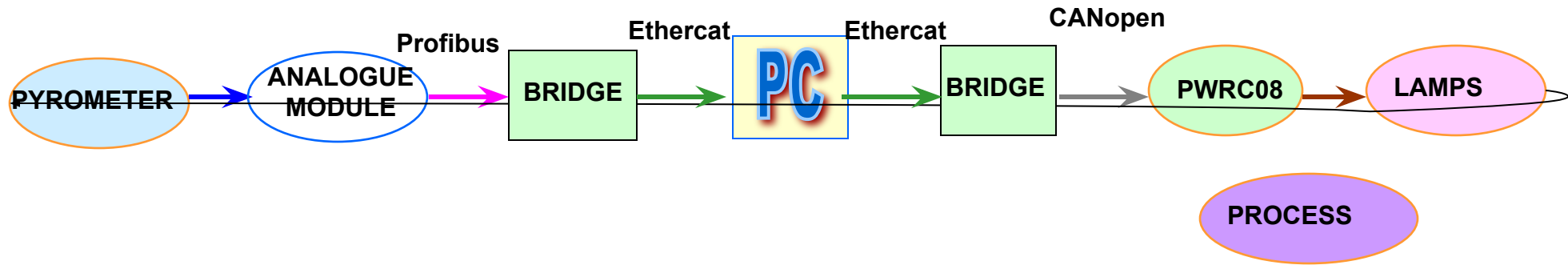


IRAZ24 CARD

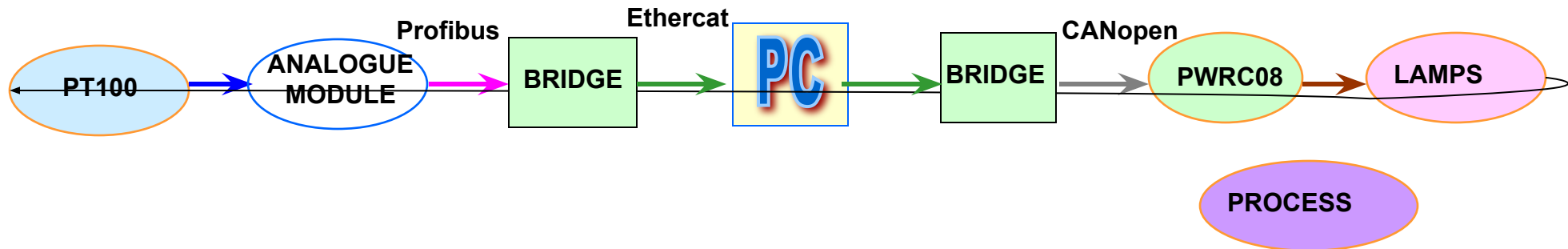


HEATINGS MANAGEMENT - PWRC08

PREFORM TEMPERATURE CONTROL

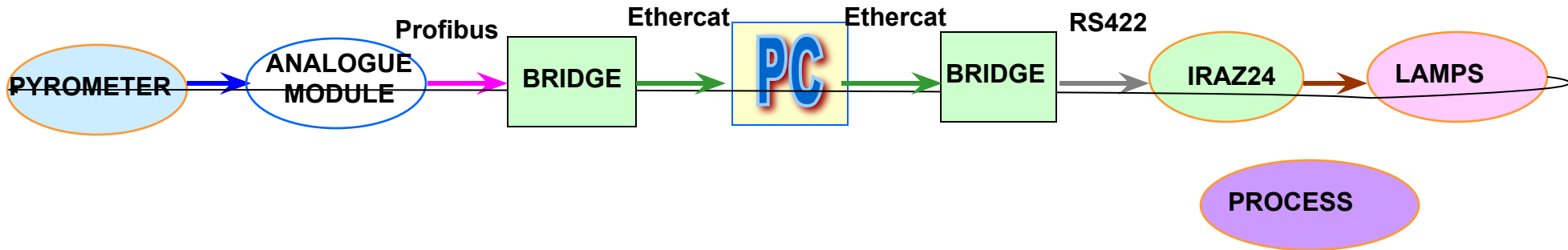


OVEN AIR TEMPERATURE CONTROL

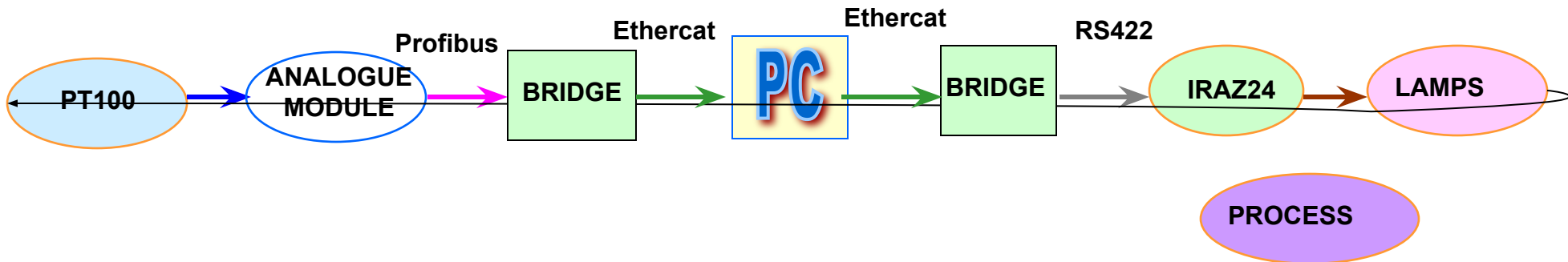


HEATINGS MANAGEMENT - IRAZZ24

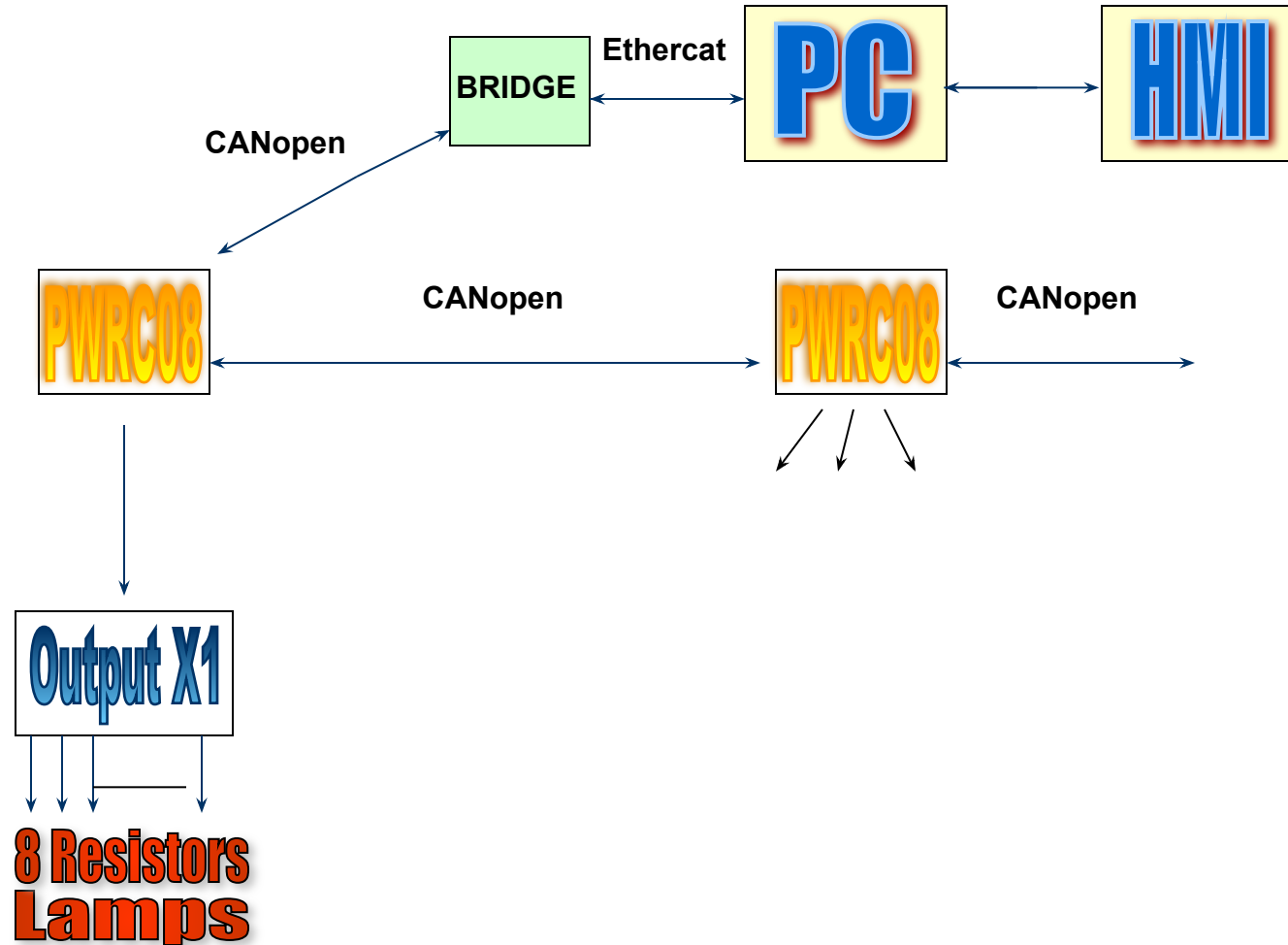
PREFORM TEMPERATURE CONTROL



OVEN AIR TEMPERATURE CONTROL



HEATINGS MANAGEMENT - PWRC08



HEATINGS MANAGEMENT - IRAZ24

