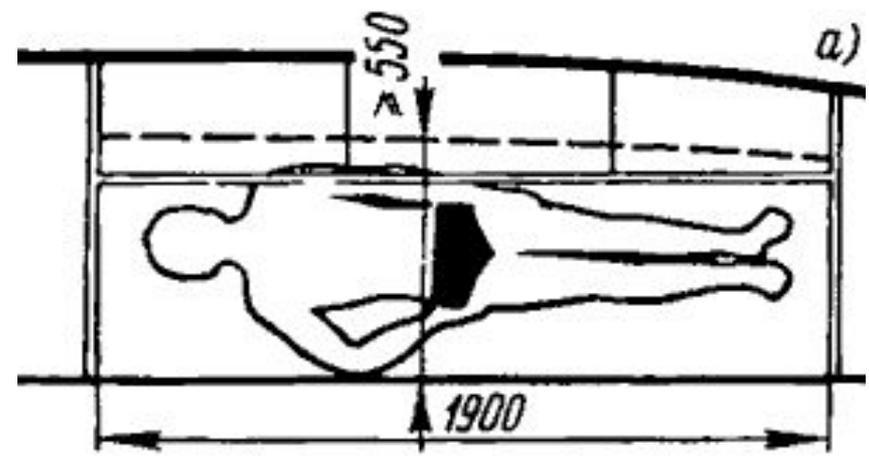
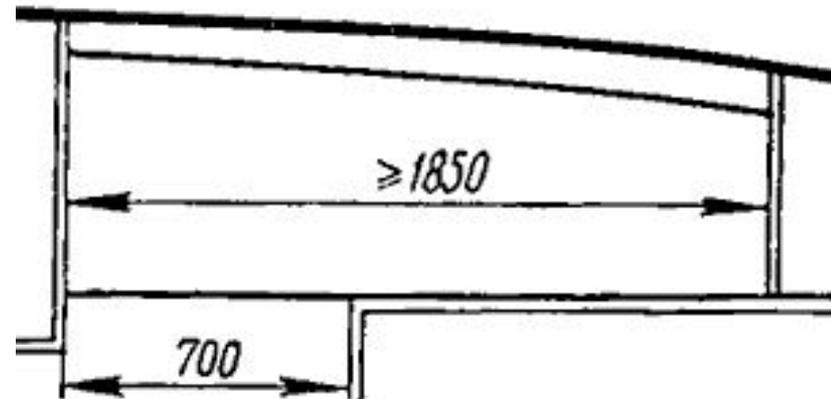
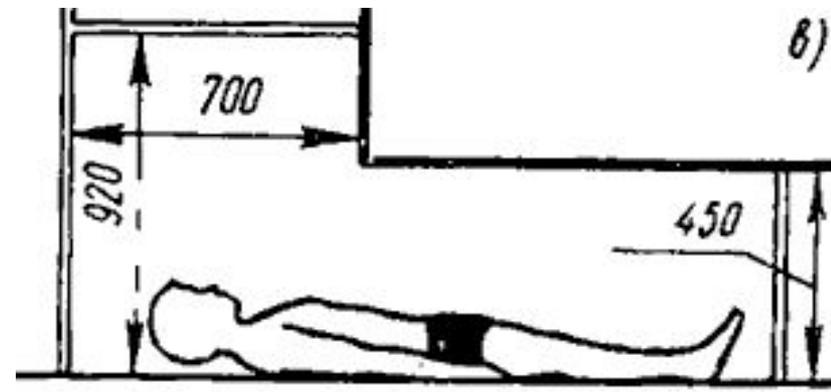
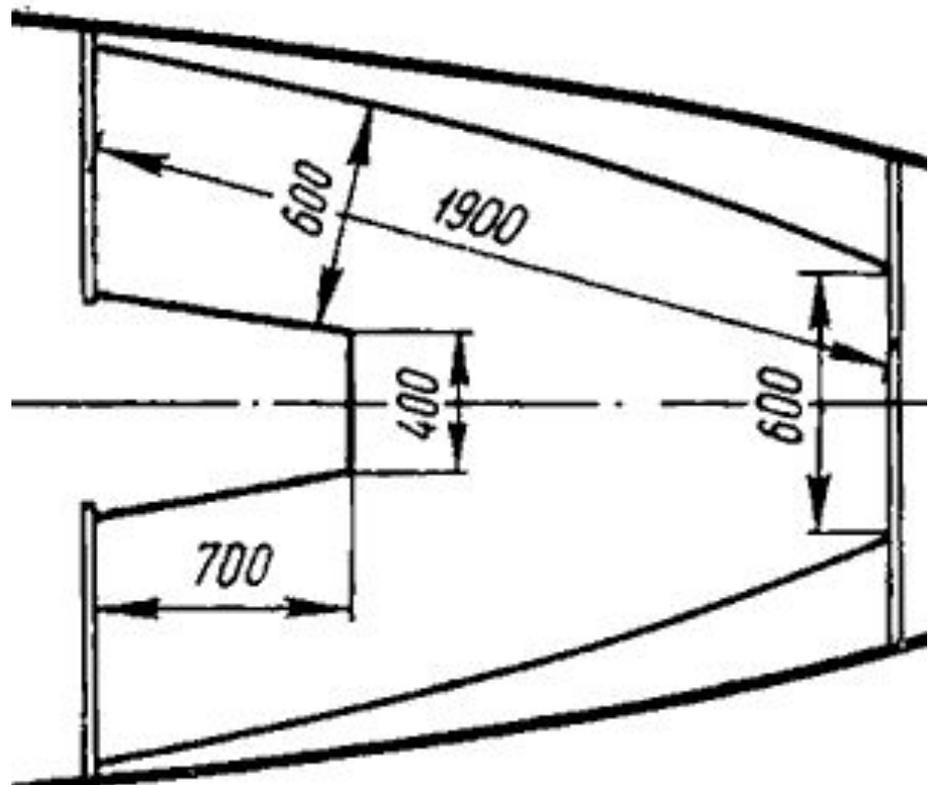
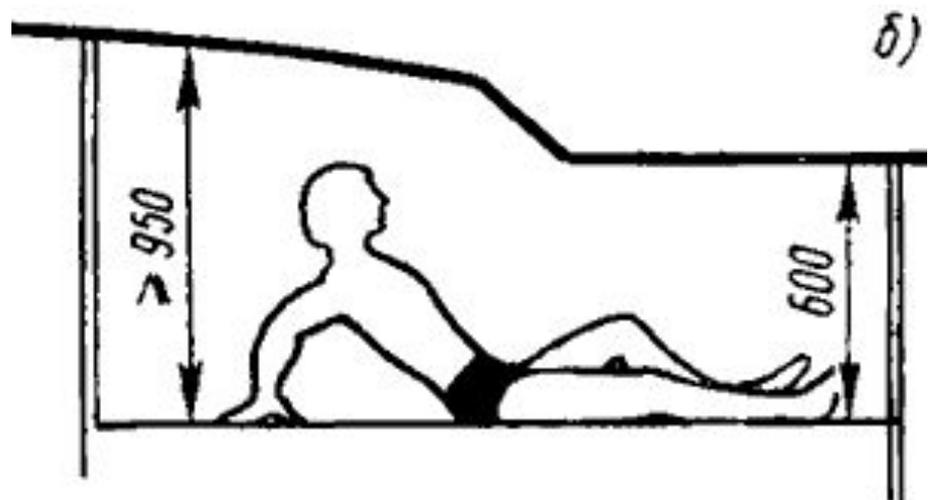
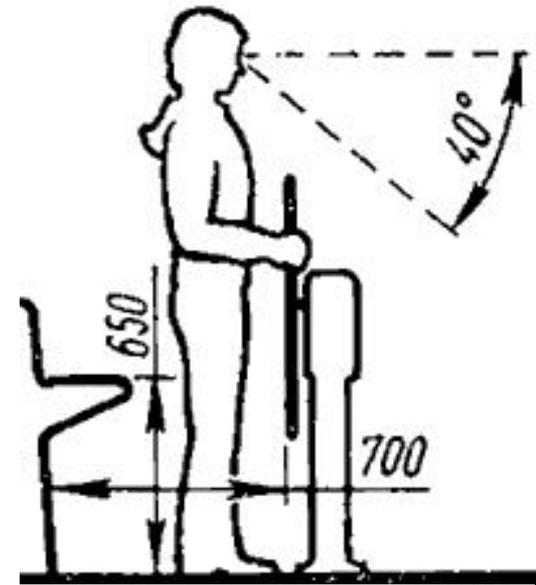
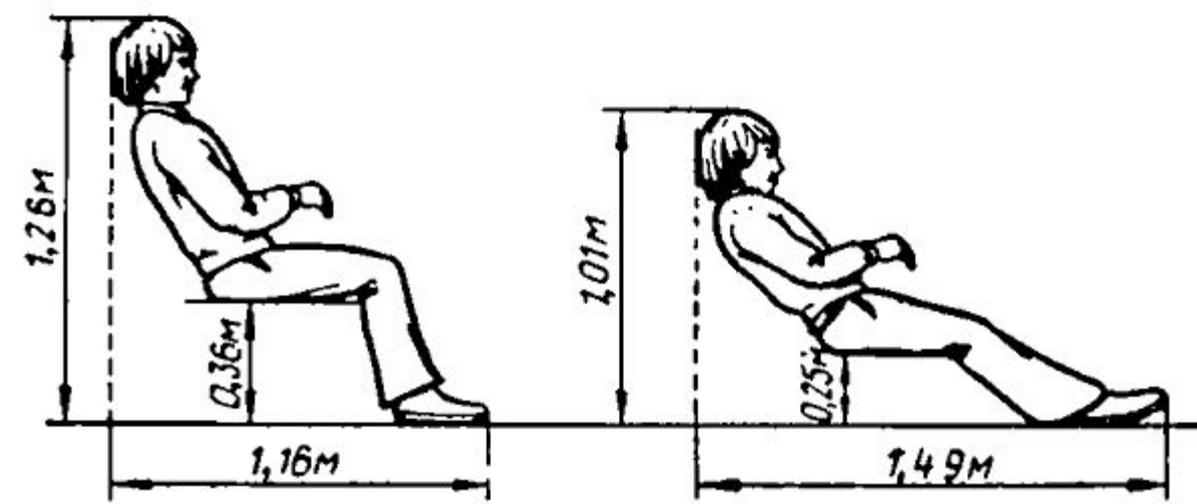
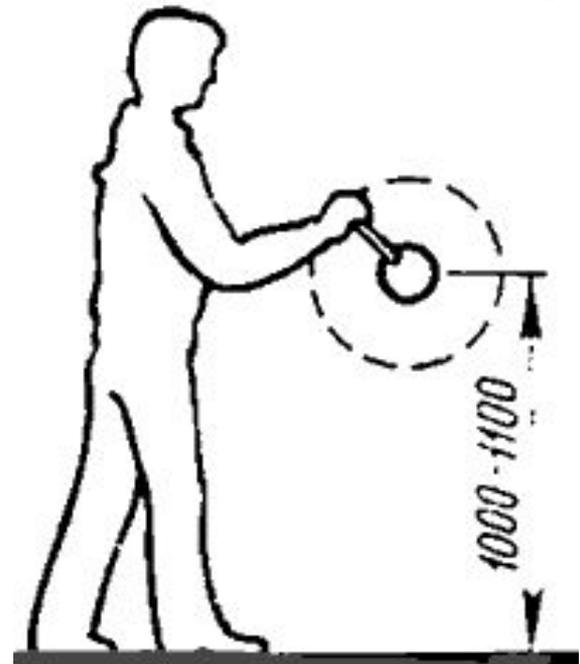
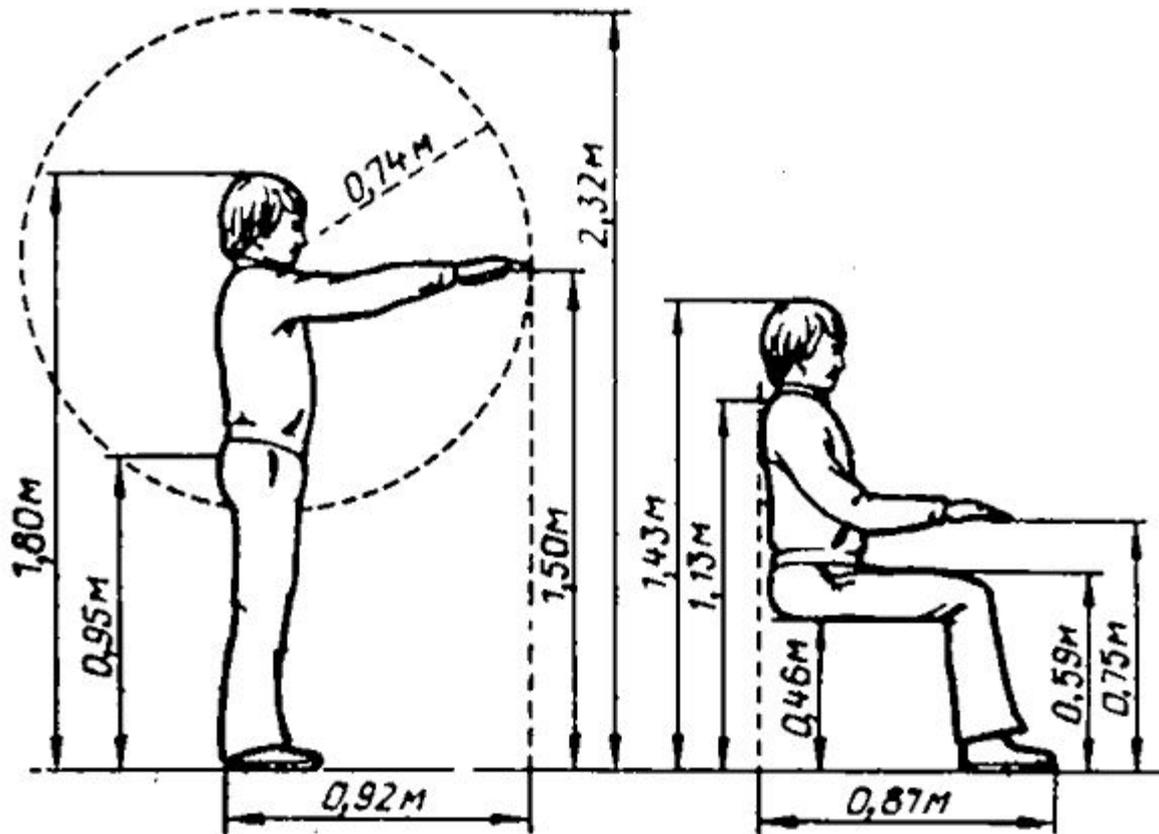


Габаритные схемы, используемые для дизайна элементов яхт и катеров





e)



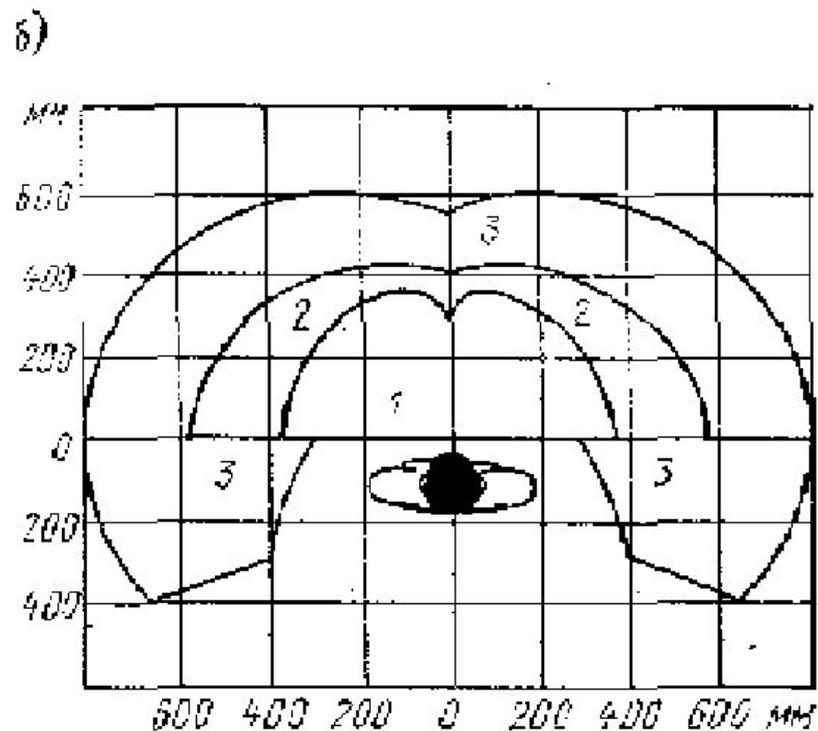
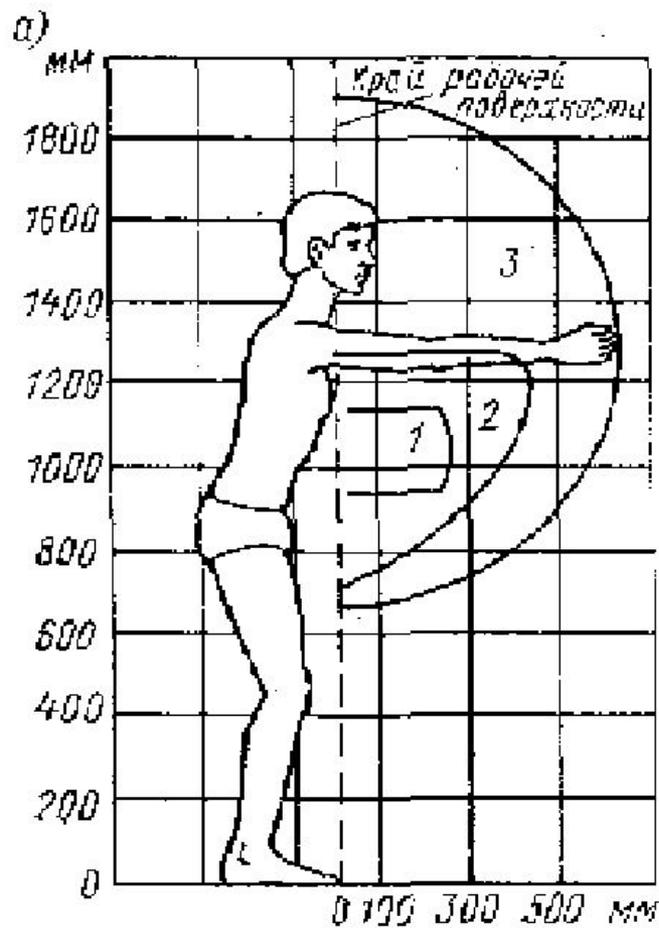
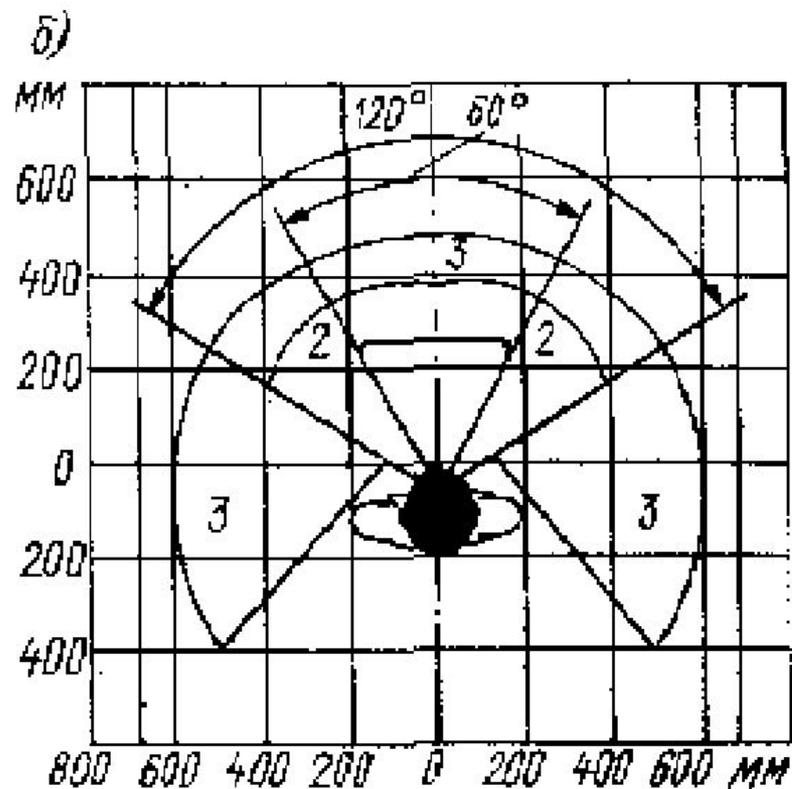
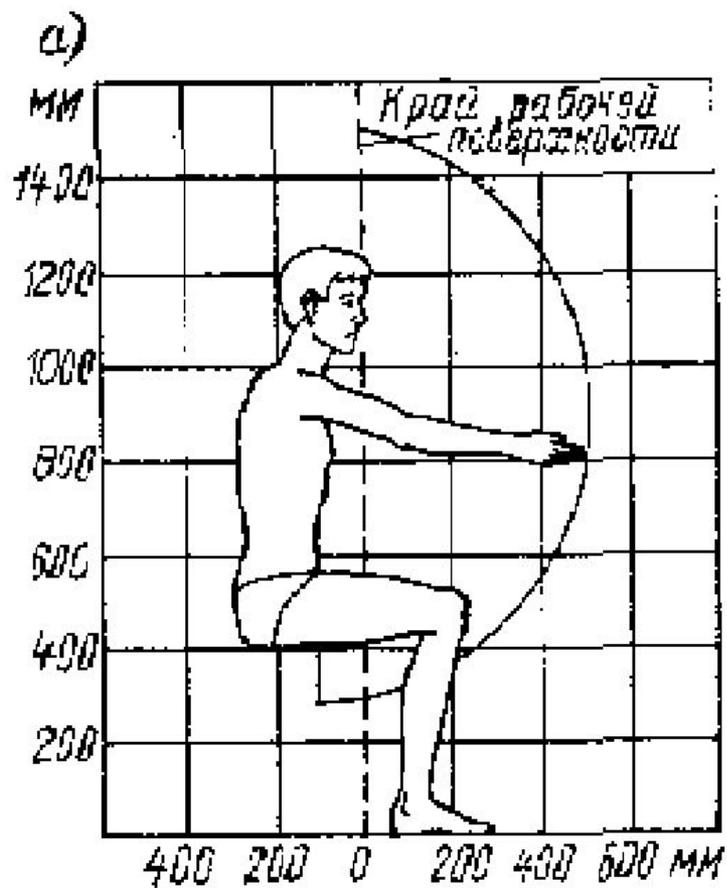
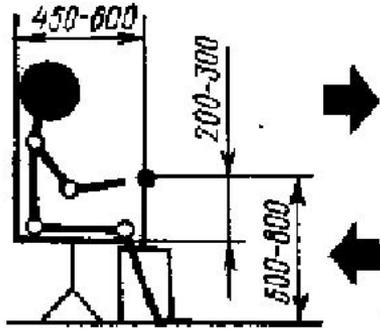
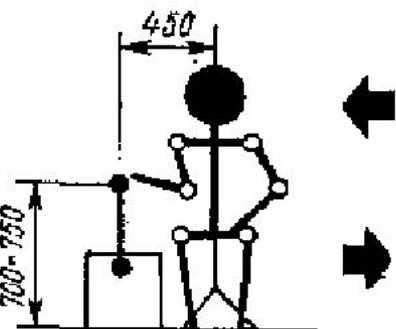
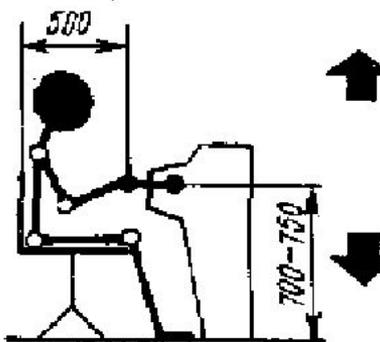
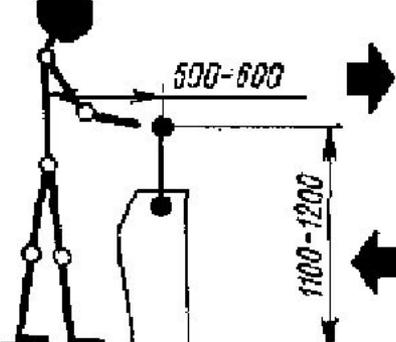
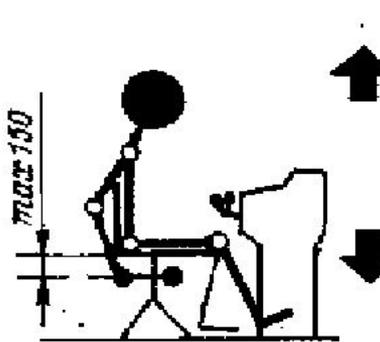
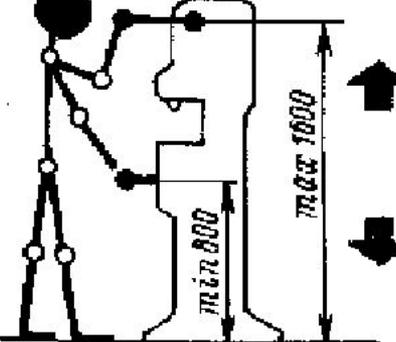
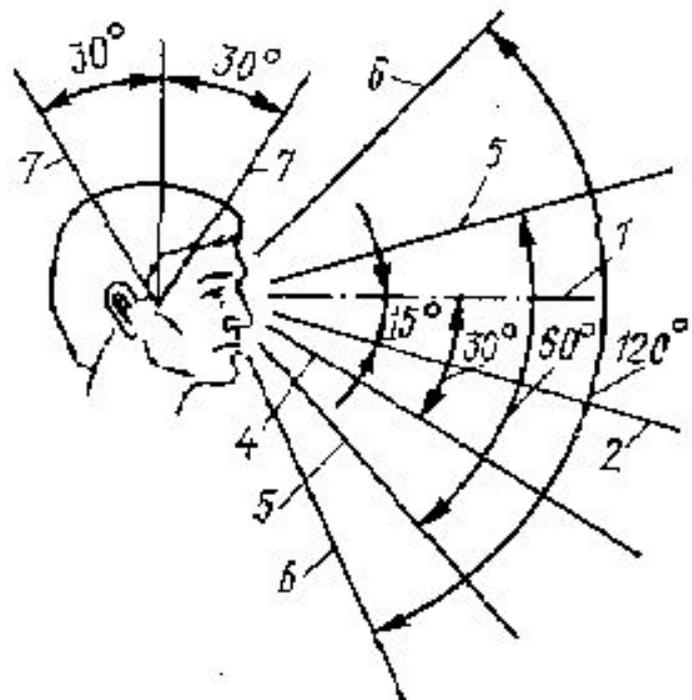


Рис. 4.4. Зоны для выполнения ручных операций в вертикальной (а) и горизонтальной (б) плоскостях при работе стоя.

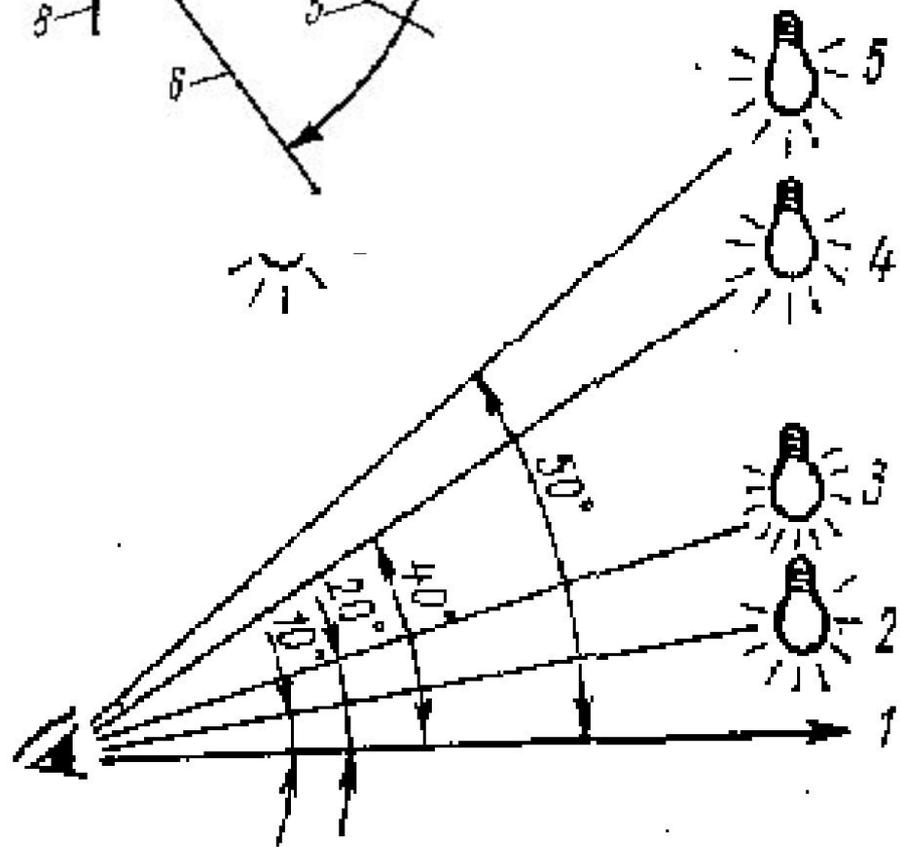
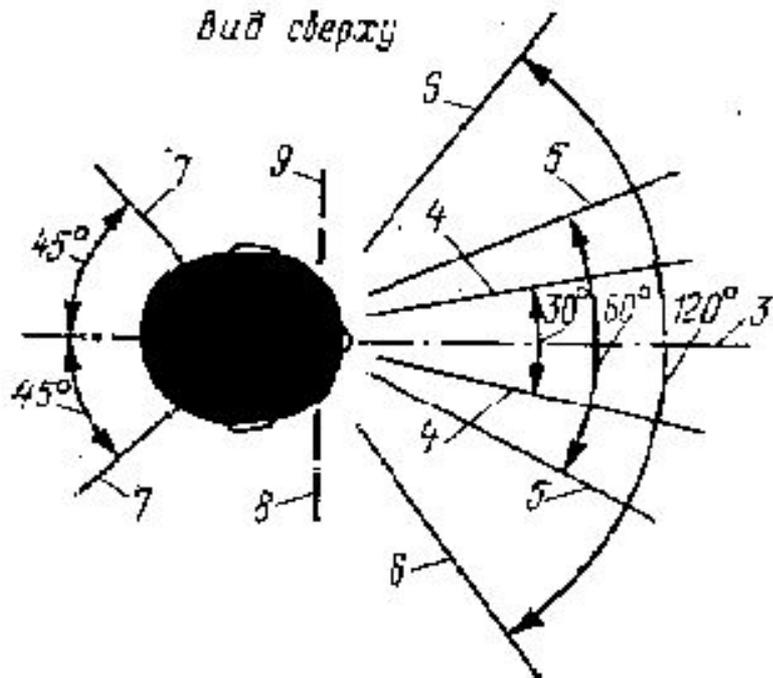
1 — оптимальная зона моторного поля; 2 — зона легкой досягаемости моторного поля; 3 — зона досягаемости моторного поля.

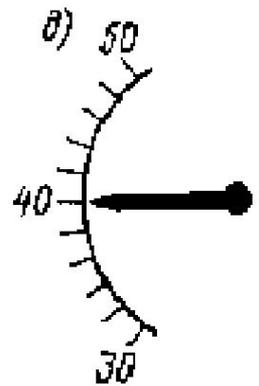
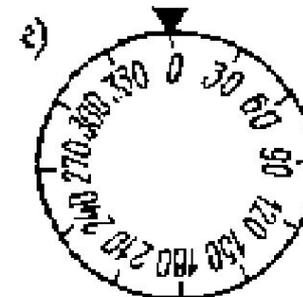
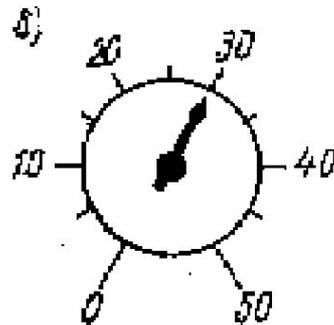
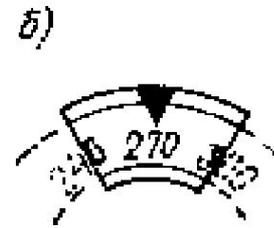
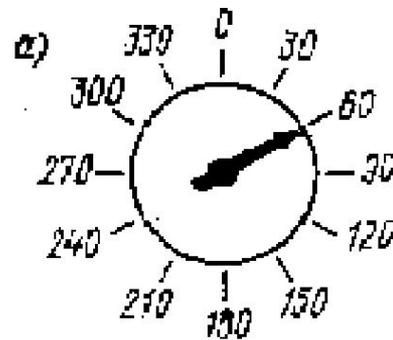
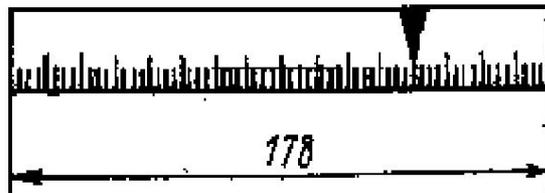
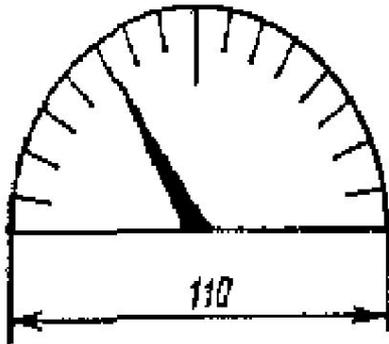
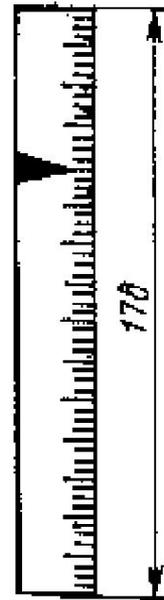
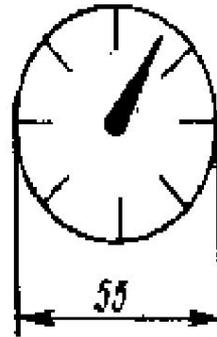
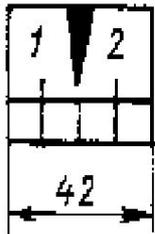


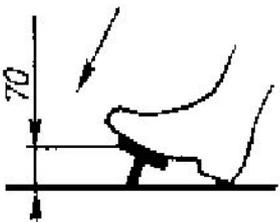
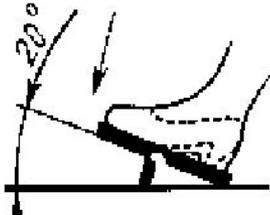
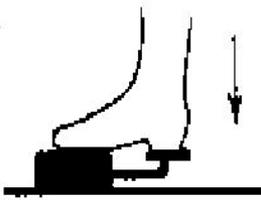
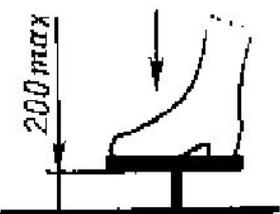
Расположение рычага и направление движения	Максимальное усилие, Н	Расположение рычага и направление его движения	Максимальное усилие, Н
	600		150
	200		400
	600		300
	300		300



Вид сверху





Форма органа управления	Рекомендуемая сила, Н		Форма органа управления	Рекомендуемая сила, Н	
	стоя	сидя		стоя	сидя
	150	30-60		80-100	20
	120	30-60		140	40-90
	200	70-80		20	20

